Boosting: Combining Classifiers

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The most material of this part come from: http://sifaka.cs.uiuc.edu/taotao/stat/chap10.ppt

Boosting



• INTUITION (三个臭皮匠,顶个诸葛亮)

- Combining Predictions of an ensemble is more accurate than a single classifier
- Reasons
 - Easy to find quite correct "rules of thumb" however hard to find single highly accurate prediction rule.
 - If the training examples are few and the hypothesis space is large then there are several equally accurate classifiers.
 - Hypothesis space does not contain the true function, but it has several good approximations.
 - Exhaustive global search in the hypothesis space is expensive so we can combine the predictions of several locally accurate classifiers.

Cross Validation



- k-fold Cross Validation
 - Divide the data set into k sub samples
 - Use k-1 sub samples as the training data and one sub sample as the test data.
 - Repeat the second step by choosing different sub samples as the testing set.
- Leave one out Cross validation
 - Used when the training data set is small.
 - Learn several classifiers each one with one data sample left out
 - The final prediction is the aggregate of the predictions of the individual classifiers.

Bagging



- Generate a random sample from training set
- Repeat this sampling procedure, getting a sequence of K independent training sets
- A corresponding sequence of classifiers C1,C2,...,Ck is constructed for each of these training sets, by using the same classification algorithm
- To classify an unknown sample X, let each classifier predict.
- The Bagged Classifier C* then combines the predictions of the individual classifiers to generate the final outcome. (sometimes combination is simple voting)

Boosting



- The final prediction is a combination of the prediction of several predictors.
- Differences between Boosting and previous methods?
 - It is iterative.
 - Boosting: Successive classifiers depends upon its predecessors.
 - Previous methods : Individual classifiers were independent.
 - Training examples may have unequal weights.
 - Look at errors from previous classifier step to decide how to focus on next iteration over data
 - Set weights to focus more on 'hard' examples. (the ones on which we committed mistakes in the previous iterations)

$$t(\mathbf{x}) \approx \hat{f}(x) = \sum_{i=1}^{k} w_i h_i \qquad C(\mathbf{x}) = \sum_{i=1}^{k} \alpha_i C_i(\mathbf{x}; \mathbf{w}_i)$$

Boosting(Algorithm)



- W(x) is the distribution of weights over the *N* training points $\sum W(x_i)=1$
- Initially assign uniform weights W₀(x) = 1/N for all x, step k=0
- At each iteration k :
 - Find best weak classifier $C_k(x)$ using weights $W_k(x)$
 - With error rate ε_k and based on a loss function:
 - weight α_k the classifier C_k 's weight in the final hypothesis
 - For each x_i , update weights based on ε_k to get $W_{k+1}(x_i)$
- $C_{FINAL}(x) = \text{sign} [\sum \alpha_i C_i(x)]$



Boosting (Algorithm)





AdaBoost(Algorithm)

- W(x) is the distribution of weights over the *N* training points $\sum W(x_i)=1$
- Initially assign uniform weights $W_0(x) = 1/N$ for all x.
- At each iteration k :
 - Find best weak classifier $C_k(x)$ using weights $W_k(x)$
 - Compute ε_k the error rate as $\varepsilon_k = [\sum W(x_i) \cdot I(y_i \neq C_k(x_i))] / [\sum W(x_i)]$
 - weight α_k the classifier C_k 's weight in the final hypothesis Set $\alpha_k = \log ((1 \varepsilon_k)/\varepsilon_k)$
 - For each x_i , $W_{k+1}(x_i) = W_k(x_i) \cdot \exp[\alpha_k \cdot I(y_i \neq C_k(x_i))]$
- $C_{FINAL}(x) = \text{sign} [\sum \alpha_i C_i(x)]$

 $L(y, f(x)) = \exp(-y \cdot f(x))$ - the exponential loss function





Original Training set : Equal Weights to all training samples







ROUND 2





ROUND 3







Show demo ...

AdaBoost Case Study:



Rapid Object Detection using a Boosted Cascade of Simple Features (IEEE CVPR2001)

<u>Rapid object detection using a boosted cascade of simple features</u> - <u>所有 33 个版本»</u> P Viola, M Jones - IEEE COMPUTER SOCIETY CONFERENCE ON COMPUTER VISION AND …, 2001 - doi.ieeecs.org This paper describes a machine learning approach for vi- sual object detection which is capable of processing images extremely rapidly and achieving high detection rates. This work is distinguished by three key contributions. The first is the introduction of a new image representation ...

<u>被引用次数: 537</u> - <u>网页搜索</u>



Object detection using AdaBoost

- Object Detection
- Features
 - two-rectangle
 - three-rectangle
 - four-rectangle

Size: 24x24 Feature: 180,000





Integral Image





Features Computation





Using the integral image any rectangular sum can be computed in four array references **ii(4) + ii(1) – ii(2) – ii(3)**

- Given example images (x₁, y₁),..., (x_n, y_n) where y_i = 0, 1 for negative and positive examples respectively.
- Initialize weights w_{1,i} = ¹/_{2m}, ¹/_{2l} for y_i = 0, 1 respectively, where m and l are the number of negatives and positives respectively.
- For t = 1, ..., T:
 - 1. Normalize the weights,

$$w_{t,i} \leftarrow \frac{w_{t,i}}{\sum_{j=1}^{n} w_{t,j}}$$

so that w_t is a probability distribution.

- 2. For each feature, j, train a classifier h_j which is restricted to using a single feature. The error is evaluated with respect to w_t , $\epsilon_j = \sum_i w_i |h_j(x_i) - y_i|$.
- 3. Choose the classifier, h_t , with the lowest error ϵ_t .
- 4. Update the weights:

$$w_{t+1,i} = w_{t,i}\beta_t^{1-e}$$

where $e_i = 0$ if example x_i is classified correctly, $e_i = 1$ otherwise, and $\beta_t = \frac{\epsilon_t}{1 - \epsilon_t}$.

· The final strong classifier is:

$$h(x) = \begin{cases} 1 & \sum_{t=1}^{T} \alpha_t h_t(x) \ge \frac{1}{2} \sum_{t=1}^{T} \alpha_t \\ 0 & \text{otherwise} \end{cases}$$

where $\alpha_t = \log \frac{1}{\beta_t}$



AdaBoost algorithm for classifier learning











Homework

- Implement this CVPR paper.
 - Hint: You can use OpenCV.



Thank you

