Subdivision Surface (2)

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Contents

- <u>Subdivision Methods for Quadratic B-</u>
 <u>Spline Surfaces</u>
- Doo-Sabin Surfaces
- <u>Subdivision Methods for Cubic B-Spline</u>
 <u>Surfaces</u>
- <u>Catmull-Clark Surfaces</u>
- Loop Surfaces

Subdivision Methods for Quadratic B-Spline Surfaces

- <u>Overview</u>
- <u>The Matrix Equation for a Uniform</u> Biquadratic B-Spline Surface
- Subdividing the Surface
- Generating the Refinement Procedure
- <u>Summary</u>

Overview

- Subdivision surfaces are based upon the binary subdivision of the uniform B-spline surface.
 - a initial polygonal mesh + a subdivision (or refinement) operation = a new polygonal mesh that has a greater number of polygonal elements
 - it is hopefully "closer" to some resulting surface.
 - By repetitively applying the subdivision procedure to the initial mesh, we generate a sequence of meshes that (hopefully) converges to a resulting surface.



The Matrix Equation for a Uniform Biquadratic B-Spline Surface

Consider the biquadratic uniform B-spline surface P(u,v) defined by the 3×3 array of control points

$$P = \begin{bmatrix} \mathbf{P}_{0,0} & \mathbf{P}_{0,1} & \mathbf{P}_{0,2} \\ \mathbf{P}_{1,0} & \mathbf{P}_{1,1} & \mathbf{P}_{1,2} \\ \mathbf{P}_{2,0} & \mathbf{P}_{2,1} & \mathbf{P}_{2,2} \end{bmatrix} \xrightarrow{\mathbf{P}_{0,0}} \xrightarrow{\mathbf{P}_{0,1}} \xrightarrow{\mathbf{P}_{0,2}} \\ \mathbf{P}_{1,0} & \xrightarrow{\mathbf{P}_{1,1}} \xrightarrow{\mathbf{P}_{1,2}} \\ \mathbf{P}_{1,0} & \xrightarrow{\mathbf{P}_{1,2}} \xrightarrow{\mathbf{P}_{1,2}} \xrightarrow{\mathbf{P}_{1,2}} \xrightarrow{\mathbf{P}_{2,2}} \xrightarrow$$

The Matrix Equation for a Uniform Biquadratic B-Spline Surface

Biquadratic B-spline surface can be written as the following equation in matrix form

$$\mathbf{P}(u,v) = \begin{bmatrix} 1 & u & u^2 \end{bmatrix} M P M^T \begin{bmatrix} 1 \\ v \\ v^2 \end{bmatrix}$$

where *M* is the 3×3 matrix

$$M = \frac{1}{2} \begin{bmatrix} 1 & 1 & 0 \\ -2 & 2 & 0 \\ 1 & -2 & 1 \end{bmatrix}$$

- This patch can be subdivided into four subpatches, 16 sub-control points.
 - the subpatch corresponding to $0 \le u, v \le 1/2$,
 - the four "interior" control points



To subdivide the surface, we reparameterizing of the surface by u'=u/2 and v'=v/2 and define new the surface $\mathbf{P}'(u,v)$

$$\begin{aligned} \mathbf{P}'(u,v) &= \mathbf{P}\left(\frac{u}{2}, \frac{v}{2}\right) \\ &= \begin{bmatrix} 1 & \frac{u}{2} & \left(\frac{u}{2}\right)^2 \end{bmatrix} MPM^T \begin{bmatrix} 1 \\ \frac{v}{2} \\ \left(\frac{v}{2}\right)^2 \end{bmatrix} \\ &= \begin{bmatrix} 1 & u & u^2 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & \frac{1}{2} & 0 \\ 0 & 0 & \frac{1}{4} \end{bmatrix} MPM^T \begin{bmatrix} 1 & 0 & 0 \\ 0 & \frac{1}{2} & 0 \\ 0 & 0 & \frac{1}{4} \end{bmatrix}^T \begin{bmatrix} 1 \\ v \\ v^2 \end{bmatrix} \\ &= \begin{bmatrix} 1 & u & u^2 \end{bmatrix} MM^{-1} \begin{bmatrix} 1 & 0 & 0 \\ 0 & \frac{1}{2} & 0 \\ 0 & 0 & \frac{1}{4} \end{bmatrix} MPM^T \begin{bmatrix} 1 & 0 & 0 \\ 0 & \frac{1}{2} & 0 \\ 0 & 0 & \frac{1}{4} \end{bmatrix}^T (M^{-1})^T M^T \begin{bmatrix} 1 \\ v \\ v^2 \end{bmatrix} \\ &= \begin{bmatrix} 1 & u & u^2 \end{bmatrix} M \left(M^{-1} \begin{bmatrix} 1 & 0 & 0 \\ 0 & \frac{1}{2} & 0 \\ 0 & 0 & \frac{1}{4} \end{bmatrix} M \right) P \left(M^T \begin{bmatrix} 1 & 0 & 0 \\ 0 & \frac{1}{2} & 0 \\ 0 & 0 & \frac{1}{4} \end{bmatrix}^T (M^{-1})^T \right) M^T \begin{bmatrix} 1 \\ v \\ v^2 \end{bmatrix} \\ &= \begin{bmatrix} 1 & u & u^2 \end{bmatrix} M \left(M^{-1} \begin{bmatrix} 1 & 0 & 0 \\ 0 & \frac{1}{2} & 0 \\ 0 & 0 & \frac{1}{4} \end{bmatrix} M \right) P \left(M^{-1} \begin{bmatrix} 1 & 0 & 0 \\ 0 & \frac{1}{2} & 0 \\ 0 & 0 & \frac{1}{4} \end{bmatrix} M \right)^T M^T \begin{bmatrix} 1 \\ v \\ v^2 \end{bmatrix} \\ &= \begin{bmatrix} 1 & u & u^2 \end{bmatrix} M P'M^T \begin{bmatrix} 1 \\ v \\ v^2 \end{bmatrix} \end{aligned}$$

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where
$$P' = SPS^{T}$$
, and
 $S = M^{-1} \begin{bmatrix} 1 & 0 & 0 \\ 0 & \frac{1}{2} & 0 \\ 0 & 0 & \frac{1}{4} \end{bmatrix} M$

The surface $\mathbf{P}'(u,v)$ is written as

$$\mathbf{P}'(u,v) = \begin{bmatrix} 1 & u & u^2 \end{bmatrix} M P' M^T \begin{bmatrix} 1 \\ v \\ v^2 \end{bmatrix}$$

The $\mathbf{P}'(u,v)$ is a uniform biquadratic B-spline patch

The matrix *S* is called the "splitting matrix", and is given by

$$S = \frac{1}{2} \begin{bmatrix} 2 & -1 & 0 \\ 2 & 1 & 0 \\ 2 & 3 & 4 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & \frac{1}{2} & 0 \\ 0 & 0 & \frac{1}{4} \end{bmatrix} \frac{1}{2} \begin{bmatrix} 1 & 1 & 0 \\ -2 & 2 & 0 \\ 1 & -2 & 1 \end{bmatrix}$$
$$= \frac{1}{4} \begin{bmatrix} 3 & 1 & 0 \\ 1 & 3 & 0 \\ 0 & 3 & 1 \end{bmatrix}$$

The new control point mesh $P'=SPS^T$ corresponding to the subdivided patch

$$S = \frac{1}{2} \begin{bmatrix} 2 & -1 & 0 \\ 2 & 1 & 0 \\ 2 & 3 & 4 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & \frac{1}{2} & 0 \\ 0 & 0 & \frac{1}{4} \end{bmatrix} \frac{1}{2} \begin{bmatrix} 1 & 1 & 0 \\ -2 & 2 & 0 \\ 1 & -2 & 1 \end{bmatrix}$$
$$= \frac{1}{4} \begin{bmatrix} 3 & 1 & 0 \\ 1 & 3 & 0 \\ 0 & 3 & 1 \end{bmatrix}$$

The $\mathbf{P'}_{i,i}$ can be written as $\mathbf{P}_{0,0}' = \frac{1}{16} \left(3(3\mathbf{P}_{0,0} + \mathbf{P}_{1,0}) + (3\mathbf{P}_{0,1} + \mathbf{P}_{1,1}) \right)$ $\mathbf{P}_{0,1}' = \frac{1}{16} \left((3\mathbf{P}_{0,0} + \mathbf{P}_{1,0}) + 3(3\mathbf{P}_{0,1} + \mathbf{P}_{1,1}) \right)$ $\mathbf{P}_{0,2}' = \frac{1}{16} \left(3(3\mathbf{P}_{0,1} + \mathbf{P}_{1,1}) + (3\mathbf{P}_{0,2} + \mathbf{P}_{1,2}) \right)$ $\mathbf{P}_{1,0}' = \frac{1}{16} \left(3(\mathbf{P}_{0,0} + 3\mathbf{P}_{1,0}) + (\mathbf{P}_{0,1} + 3\mathbf{P}_{1,1}) \right)$ $\mathbf{P}_{1,1}' = \frac{1}{16} \left((\mathbf{P}_{0,0} + 3\mathbf{P}_{1,0}) + 3(\mathbf{P}_{0,1} + 3\mathbf{P}_{1,1}) \right)$ $\mathbf{P}_{1,2}' = \frac{1}{16} \left(3(\mathbf{P}_{0,1} + 3\mathbf{P}_{1,1}) + (\mathbf{P}_{0,2} + 3\mathbf{P}_{1,2}) \right)$ $\mathbf{P}_{2,0}' = \frac{1}{16} \left(3(3\mathbf{P}_{1,0} + \mathbf{P}_{2,0}) + (3\mathbf{P}_{1,1} + \mathbf{P}_{2,1}) \right)$ $\mathbf{P}_{2,1}' = \frac{1}{16} \left((3\mathbf{P}_{1,0} + \mathbf{P}_{2,0}) + 3(3\mathbf{P}_{1,1} + \mathbf{P}_{2,1}) \right)$ $\mathbf{P}'_{2,2} = \frac{1}{16} \left(3(3\mathbf{P}_{1,1} + \mathbf{P}_{2,1}) + (3\mathbf{P}_{1,2} + \mathbf{P}_{2,2}) \right)$

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- These equations can be looked at in two ways
 - Subdivision masks: weighing the four points in the ratio of 9-3-3-1

Extension of Chaikin's curve to surface: each of these equations is built from weighing the points on an edge in the ratio of 3-1. and then weighing the resulting points in the ratio 3-1

Generating the Refinement Procedure

 All 16 of the possible points generated through the binary subdivision of the quadratic patch can be defined by the same subdivision masks



Generating the Refinement Procedure



Summary

- The extension of Chaikin's Curve to surfaces
- Non-rectangular topological structure
 Doo-Sabin surfaces by Donald Doo and Malcolm Sabin



Doo-Sabin Surfaces



Doo-Sabin Surfaces

- <u>The Procedure for the Biquadratic Uniform</u>
 <u>B-Spline Patch</u>
- <u>The Procedure for Meshes of Arbitrary</u>
 <u>Topology</u>
- <u>Illustrations</u>
- <u>Summary</u>



Malcolm Sabin

The Procedure for the Biquadratic Uniform B-Spline Patch

 The subdivision masks for the biquadratic uniform Bspline patches

- Each new points are simply the average of four particular points taken in a polygon
 - the corresponding original point
 - the two edge points (the midpoints of the edges that are adjacent to this vertex in the polygon)
 - the face point (average of the vertices of the polygon)

The Procedure for the Biquadratic Uniform B-Spline Patch



For each vertex P_i of each face of the object, generate a new point P'_i as average of the vertex, the two edge points and the face point of the face



• For each face, connect the new points that have been generated for each vertex of the face.



• For each vertex, connect the new points that have been generated for the faces that are adjacent to this vertex.



• For each edge, connect the new points that have been generated for the faces that are adjacent to this edge.



 The polygons generated through this refinement step become the set of polygons for the next step.

Note: the "cutting off the corners" of the polygonal mesh





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- extraordinary points
 - Not 4 edges emitted from the point
- after the first subdivision, all vertices have valence four





Doo-Sabin Subdivision Surface



Summary

- The algorithm defines new points on each face in the refinement process, these new points only depend on
 - the face point
 - the vertex on a face
 - two edge midpoints for edges adjacent to the vertex
- The Doo-Sabin surface is locally a bi-quadratic B-spline surface, except at a finite number of extraordinary control points.

Subdivision Methods for Cubic B-Spline Surfaces

- <u>Overview</u>
- <u>A Matrix Equation for the Bicubic Uniform</u>
 <u>Spline Surfaces</u>
- Subdividing the Bicubic Patch
- Extending this Subdivision Procedure to the Entire Patch
- <u>Summary</u>

Overview

- Ed Catmull and Jim Clark: extend Doo and Sabin's algorithm to bicubic surfaces.
 - The methods of Doo-Sabin algorithm: binary subdivision of the uniform bi-quadratic Bspline patches.
 - Study of the cubic case would lead to a better subdivision surface generation scheme.



A Matrix Equation for the Bicubic Uniform Spline Surfaces

Consider the biqcubic uniform B-spline surface P(u,v) defined by the 4×4 array of control points

$$P = \begin{bmatrix} \mathbf{P}_{0,0} & \mathbf{P}_{0,1} & \mathbf{P}_{0,2} & \mathbf{P}_{0,3} \\ \mathbf{P}_{1,0} & \mathbf{P}_{1,1} & \mathbf{P}_{1,2} & \mathbf{P}_{1,3} \\ \mathbf{P}_{2,0} & \mathbf{P}_{2,1} & \mathbf{P}_{2,2} & \mathbf{P}_{2,3} \\ \mathbf{P}_{3,0} & \mathbf{P}_{3,1} & \mathbf{P}_{3,2} & \mathbf{P}_{3,3} \end{bmatrix}$$

A Matrix Equation for the Bicubic Uniform Spline Surfaces



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A Matrix Equation for the Bicubic Uniform Spline Surfaces

where

$$\mathbf{P}(u,v) = \begin{bmatrix} 1 & u & u^2 & u^3 \end{bmatrix} M P M^T \begin{bmatrix} 1 \\ v \\ v^2 \\ v^3 \end{bmatrix}$$
where M is the 4×4 matrix

where *M* is the 4×4 matrix

$$M = \frac{1}{6} \begin{bmatrix} 1 & 4 & 1 & 0 \\ -3 & 0 & 3 & 0 \\ 3 & -6 & 3 & 0 \\ -1 & 3 & -3 & 1 \end{bmatrix}$$
- The bicubic uniform B-spline patch can be subdivided into
 - four subpatches $(1 \rightarrow 4)$
 - 25 unique sub-control points $(16 \rightarrow 25)$
- Focus on the subpatch corresponding to $0 \le u, v \le 1/2$
 - the others will follow by symmetry



To subdivide the surface, we reparameterizing of the surface by u'=u/2 and v'=v/2 and define new the surface $\mathbf{P}'(u,v)$

$$\begin{aligned} \mathbf{P}^{\prime}(u,v) &= \mathbf{P}(\frac{u}{2}, \frac{v}{2}) \\ &= \begin{bmatrix} 1 & \frac{u}{2} & (\frac{u}{2})^2 & (\frac{u}{2})^3 \end{bmatrix} MPM^T \begin{bmatrix} 1 \\ \frac{v}{2} \\ (\frac{u}{2})^2 \\ (\frac{v}{2})^3 \end{bmatrix} \\ &= \begin{bmatrix} 1 & u & u^2 & u^3 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & \frac{1}{2} & 0 & 0 \\ 0 & 0 & \frac{1}{4} & 0 \\ 0 & 0 & 0 & \frac{1}{8} \end{bmatrix} MPM^T \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & \frac{1}{2} & 0 & 0 \\ 0 & 0 & 0 & \frac{1}{8} \end{bmatrix}^T \begin{bmatrix} 1 \\ v \\ v^2 \\ v^3 \end{bmatrix} \\ &= \begin{bmatrix} 1 & u & u^2 & u^3 \end{bmatrix} MM^{-1} \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & \frac{1}{2} & 0 & 0 \\ 0 & 0 & \frac{1}{4} & 0 \\ 0 & 0 & 0 & \frac{1}{8} \end{bmatrix} MPM^T \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & \frac{1}{2} & 0 & 0 \\ 0 & 0 & \frac{1}{4} & 0 \\ 0 & 0 & 0 & \frac{1}{8} \end{bmatrix}^T (M^{-1})^T M^T \begin{bmatrix} 1 \\ v \\ v^2 \\ v^3 \end{bmatrix} \\ &= \begin{bmatrix} 1 & u & u^2 & u^3 \end{bmatrix} MSPS^T M^T \begin{bmatrix} 1 \\ v \\ v^2 \\ v^3 \end{bmatrix} \\ &= \begin{bmatrix} 1 & u & u^2 & u^3 \end{bmatrix} MP'M^T \begin{bmatrix} 1 \\ v \\ v^2 \\ v^3 \end{bmatrix} \end{aligned}$$

12/

40

where $P' = SPS^T$, and

$$S = M^{-1} \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & \frac{1}{2} & 0 & 0 \\ 0 & 0 & \frac{1}{4} & 0 \\ 0 & 0 & 0 & \frac{1}{8} \end{bmatrix} M$$

The surface $\mathbf{P}'(u,v)$ is written as

$$\mathbf{P}'(u,v) = \begin{bmatrix} 1 & u & u^2 & u^3 \end{bmatrix} M P' M^T \begin{bmatrix} 1 \\ v \\ v^2 \\ v^3 \end{bmatrix}$$

12/28/2006

The P'(u,v) is a uniform bicubic B-spline patch The matrix *S* is called the "splitting matrix", and is given by

$$S = \frac{1}{8} \begin{bmatrix} 4 & 4 & 0 & 0 \\ 1 & 6 & 1 & 0 \\ 0 & 4 & 4 & 0 \\ 0 & 1 & 6 & 1 \end{bmatrix}$$

The control point array P'

$$P' = \frac{1}{8} \begin{bmatrix} 4 & 4 & 0 & 0 \\ 1 & 6 & 1 & 0 \\ 0 & 4 & 4 & 0 \\ 0 & 1 & 6 & 1 \end{bmatrix} \begin{bmatrix} \mathbf{P}_{0,0} & \mathbf{P}_{0,1} & \mathbf{P}_{0,2} & \mathbf{P}_{0,3} \\ \mathbf{P}_{1,0} & \mathbf{P}_{1,1} & \mathbf{P}_{1,2} & \mathbf{P}_{1,3} \\ \mathbf{P}_{2,0} & \mathbf{P}_{2,1} & \mathbf{P}_{2,2} & \mathbf{P}_{2,3} \\ \mathbf{P}_{3,0} & \mathbf{P}_{3,1} & \mathbf{P}_{3,2} & \mathbf{P}_{3,3} \end{bmatrix}^{1} \frac{1}{8} \begin{bmatrix} 4 & 4 & 0 & 0 \\ 1 & 6 & 1 & 0 \\ 0 & 4 & 4 & 0 \\ 0 & 1 & 6 & 1 \end{bmatrix}^{T}$$
$$= \frac{1}{8} \begin{bmatrix} 4\mathbf{P}_{0,0} + 4\mathbf{P}_{1,0} & 4\mathbf{P}_{0,1} + 4\mathbf{P}_{1,1} & 4\mathbf{P}_{0,2} + 4\mathbf{P}_{1,2} & 4\mathbf{P}_{0,3} + 4\mathbf{P}_{1,3} \\ \mathbf{P}_{0,0} + 6\mathbf{P}_{1,0} + \mathbf{P}_{2,0} & \mathbf{P}_{0,1} + 6\mathbf{P}_{1,1} + \mathbf{P}_{2,1} & \mathbf{P}_{0,2} + 6\mathbf{P}_{1,2} + \mathbf{P}_{2,2} & \mathbf{P}_{0,3} + 6\mathbf{P}_{1,3} + \mathbf{P}_{2,3} \\ 4\mathbf{P}_{1,0} + 4\mathbf{P}_{2,0} & 4\mathbf{P}_{1,1} + 4\mathbf{P}_{2,1} & 4\mathbf{P}_{1,2} + 4\mathbf{P}_{2,2} & 4\mathbf{P}_{1,3} + 4\mathbf{P}_{2,3} \\ \mathbf{P}_{1,0} + 6\mathbf{P}_{2,0} + \mathbf{P}_{3,0} & \mathbf{P}_{1,1} + 6\mathbf{P}_{2,1} + \mathbf{P}_{3,1} & \mathbf{P}_{1,2} + 6\mathbf{P}_{2,2} + \mathbf{P}_{3,2} & \mathbf{P}_{1,3} + 6\mathbf{P}_{2,3} + \mathbf{P}_{3,3} \end{bmatrix} \frac{1}{8} \begin{bmatrix} 4 & 1 & 0 & 0 \\ 4 & 6 & 4 & 1 \\ 0 & 1 & 4 & 6 \\ 0 & 0 & 6 & 1 \end{bmatrix}$$

Calculating above matrix multiplication, we can obtain

12/28/2006

$$\begin{array}{lcl} \mathbf{P}_{0,0}' &=& \displaystyle \frac{\mathbf{P}_{0,0} + \mathbf{P}_{1,0} + \mathbf{P}_{0,1} + \mathbf{P}_{1,1}}{4} \\ \\ \mathbf{P}_{0,1}' &=& \displaystyle \frac{\mathbf{P}_{0,0} + \mathbf{P}_{1,0} + 6(\mathbf{P}_{0,1} + \mathbf{P}_{1,1}) + \mathbf{P}_{0,2} + \mathbf{P}_{1,2}}{16} \\ \\ \mathbf{P}_{0,2}' &=& \displaystyle \frac{\mathbf{P}_{0,1} + \mathbf{P}_{1,1} + \mathbf{P}_{0,2} + \mathbf{P}_{1,2}}{4} \\ \\ \mathbf{P}_{0,3}' &=& \displaystyle \frac{\mathbf{P}_{0,1} + \mathbf{P}_{1,1} + 6(\mathbf{P}_{0,2} + \mathbf{P}_{1,2}) + \mathbf{P}_{0,3} + \mathbf{P}_{1,3}}{16} \\ \\ \mathbf{P}_{1,0}' &=& \displaystyle \frac{\mathbf{P}_{0,0} + \mathbf{P}_{0,1} + 6(\mathbf{P}_{1,0} + \mathbf{P}_{1,1}) + \mathbf{P}_{2,0} + \mathbf{P}_{2,1}}{16} \\ \\ \mathbf{P}_{1,1}' &=& \displaystyle \frac{\mathbf{P}_{0,0} + 6\mathbf{P}_{1,0} + \mathbf{P}_{2,0} + 6(\mathbf{P}_{0,1} + 6\mathbf{P}_{1,1} + \mathbf{P}_{2,1}) + \mathbf{P}_{0,2} + 6\mathbf{P}_{1,2} + \mathbf{P}_{2,2}}{64} \\ \\ \mathbf{P}_{1,2}' &=& \displaystyle \frac{\mathbf{P}_{0,1} + \mathbf{P}_{0,2} + 6(\mathbf{P}_{1,1} + \mathbf{P}_{1,2}) + \mathbf{P}_{2,1} + \mathbf{P}_{2,2}}{16} \\ \\ \mathbf{P}_{1,3}' &=& \displaystyle \frac{\mathbf{P}_{0,1} + 6\mathbf{P}_{1,1} + \mathbf{P}_{2,1} + 6(\mathbf{P}_{0,2} + 6\mathbf{P}_{1,2} + \mathbf{P}_{2,2}) + \mathbf{P}_{0,3} + 6\mathbf{P}_{1,3} + \mathbf{P}_{2,3}}{64} \end{array}$$

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- Each of these refined points can be classified into three categories
 - face points
 - edge points
 - vertex points

Face point: the average of the four points that bound the respective face (P₀₀', P₀₂', P₂₀' and P₂₂')



• In general, the face point $\mathbf{F}_{i,j}$

$$\mathbf{F}_{i,j} = (\mathbf{P}_{i,j} + \mathbf{P}_{i+1,j} + \mathbf{P}_{i,j+1} + \mathbf{P}_{i+1,j+1})/4$$

 we can rewrite the above equations with these face points substituted on the righthand side, and obtain

$$\begin{array}{lcl} \mathbf{P}_{0,0}' &=& \mathbf{F}_{0,0} \\ \mathbf{P}_{0,1}' &=& \frac{4\mathbf{F}_{0,0} + 4\mathbf{F}_{0,1} + 4\mathbf{P}_{0,1} + 4\mathbf{P}_{1,1}}{16} \\ \mathbf{P}_{0,2}' &=& \mathbf{F}_{0,1} \\ \mathbf{P}_{0,3}' &=& \frac{4\mathbf{F}_{0,1} + 4\mathbf{F}_{0,2} + 4\mathbf{P}_{0,2} + 4\mathbf{P}_{1,2}}{16} \\ \mathbf{P}_{1,0}' &=& \frac{4\mathbf{F}_{0,0} + 4\mathbf{F}_{1,0} + 4\mathbf{P}_{1,0} + 4\mathbf{P}_{1,1}}{16} \\ \mathbf{P}_{1,1}' &=& \frac{4\mathbf{F}_{0,0} + 4\mathbf{F}_{0,1} + 4\mathbf{F}_{1,0} + 4\mathbf{F}_{1,1} + 4\mathbf{P}_{1,0} + 4\mathbf{P}_{0,1} + 32\mathbf{P}_{1,1} + 4\mathbf{P}_{2,1} + 4\mathbf{P}_{1,2}}{64} \\ \mathbf{P}_{1,2}' &=& \frac{4\mathbf{F}_{0,1} + 4\mathbf{F}_{1,1} + 4\mathbf{P}_{1,1} + 4\mathbf{P}_{1,2}}{16} \\ \mathbf{P}_{1,3}' &=& \frac{4\mathbf{F}_{0,1} + 4\mathbf{F}_{0,2} + 4\mathbf{F}_{1,1} + 4\mathbf{F}_{1,2} + 4\mathbf{P}_{1,1} + 4\mathbf{P}_{0,2} + 32\mathbf{P}_{1,2} + 4\mathbf{P}_{2,2} + 4\mathbf{P}_{1,3}}{64} \end{array}$$

12/28/2006

$$\begin{aligned} \mathbf{P}_{0,0}' &= \mathbf{F}_{0,0} \\ \mathbf{P}_{0,1}' &= \frac{\mathbf{F}_{0,0} + \mathbf{F}_{0,1} + \mathbf{P}_{0,1} + \mathbf{P}_{1,1}}{4} \\ \mathbf{P}_{0,2}' &= \mathbf{F}_{0,1} \\ \mathbf{P}_{0,3}' &= \frac{\mathbf{F}_{0,1} + \mathbf{F}_{0,2} + \mathbf{P}_{0,2} + \mathbf{P}_{1,2}}{4} \\ \mathbf{P}_{1,0}' &= \frac{\mathbf{F}_{0,0} + \mathbf{F}_{1,0} + \mathbf{P}_{1,0} + \mathbf{P}_{1,1}}{4} \\ \mathbf{P}_{1,1}' &= \frac{\mathbf{F}_{0,0} + \mathbf{F}_{0,1} + \mathbf{F}_{1,0} + \mathbf{F}_{1,1} + \mathbf{P}_{0,1} + 8\mathbf{P}_{1,1} + \mathbf{P}_{2,1} + \mathbf{P}_{1,2}}{16} \\ \mathbf{P}_{1,2}' &= \frac{\mathbf{F}_{0,1} + \mathbf{F}_{1,1} + \mathbf{P}_{1,1} + \mathbf{P}_{1,2}}{4} \\ \mathbf{P}_{1,3}' &= \frac{\mathbf{F}_{0,1} + \mathbf{F}_{1,2} + \mathbf{F}_{1,1} + \mathbf{F}_{1,2} + \mathbf{P}_{1,1} + \mathbf{P}_{0,2} + 8\mathbf{P}_{1,2} + \mathbf{P}_{2,2} + \mathbf{P}_{1,3}}{16} \end{aligned}$$

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• Edge points: average of

- the two points that define the original edge
- the two new face points of the faces sharing the edge

• $\mathbf{P'}_{01}$, $\mathbf{P'}_{03}$, $\mathbf{P'}_{10}$, $\mathbf{P'}_{12}$, $\mathbf{P'}_{21}$, $\mathbf{P'}_{23}$, $\mathbf{P'}_{30}$, $\mathbf{P'}_{32}$



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• The edge points $\mathbf{E}_{i,i}$ can be calculated

$$\mathbf{E}_{i,j} = \frac{\mathbf{F}_{i,j-1} + \mathbf{F}_{i,j} + \mathbf{P}_{i,j} + \mathbf{P}_{i+1,j}}{4}$$

$$\mathbf{E}_{i,j} = \frac{\mathbf{F}_{i-1,j} + \mathbf{F}_{i,j} + \mathbf{P}_{i,j} + \mathbf{P}_{i,j+1}}{4}$$

depending on which side of the edge point the two faces lie.

Replacing edge points on the right-hand side of the above equations



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• Vertex points: $\mathbf{P'}_{11}$, $\mathbf{P'}_{13}$, $\mathbf{P'}_{13}$, $\mathbf{P'}_{33}$,

$$\mathbf{P}_{i,j}' = \frac{\mathbf{Q} + 2\mathbf{R} + \mathbf{S}}{4}$$

- Q: average of the face points of the faces adjacent to the vertex point
- R: average of the midpoints of the edges adjacent to the vertex point
- S: corresponding vertex from the original mesh



For example: $\mathbf{P'}_{13}$

$$\begin{aligned} \mathbf{Q} &= \frac{\mathbf{F}_{0,1} + \mathbf{F}_{0,2} + \mathbf{F}_{1,1} + \mathbf{F}_{1,2}}{4} \\ \mathbf{R} &= \frac{\frac{\mathbf{P}_{0,2} + \mathbf{P}_{1,2}}{2} + \frac{\mathbf{P}_{1,1} + \mathbf{P}_{1,2}}{2} + \frac{\mathbf{P}_{1,3} + \mathbf{P}_{1,2}}{2} + \frac{\mathbf{P}_{2,2} + \mathbf{P}_{1,2}}{2}}{4} \\ \mathbf{S} &= \mathbf{P}_{1,2} \end{aligned}$$

- Summary: All sixteen new points of the subdivision have been characterized in terms of
 - face points,
 - edge points
 - vertex points
- A geometric method has been developed to calculate these points.

Extending this Subdivision Procedure to the Entire Patch

- One subdiviosn step:
 16 points → 25 points
- We call the mesh generated by the 25 points as a refinement of the original mesh
- Three types of new points
 face points, edge points, vertex points

Extending this Subdivision Procedure to the Entire Patch

- For each face in the original mesh, generate the new face points - which are the average of all the original points defining the face.
- For each internal edge of the original mesh (i.e. an edge not on the boundary), generate the new edge points - which are calculated as the average of four points: the two points which define the edge, and the two new face points for the faces that are adjacent to the edge.

Extending this Subdivision Procedure to the Entire Patch

- For each internal vertex of the original mesh (i.e. a vertex not on the boundary of the mesh), generate the new vertex points which are calculated as the average of Q, 2R and S
 - Q is the average of the new face points of all faces adjacent to the original vertex point
 - R is the average of the midpoints of all original edges incident on the original vertex point
 - **S** is the original vertex point.



Summary

- The subdivision of the bicubic uniform Bspline surface produces a simple procedure based upon face points, edge points and vertex points
- Catmull and Clark produce a refinement strategy that works on a mesh of arbitrary topology based on above procedure



Catmull-Clark Surfaces



Original Cube The 1st subdivision The 2nd subdivision



Edwin Catmull Jim Clark: COOL!



Edwin Catmull, President of Pixar Animation Studios



Jim Clark is the founder of Netscape Communications Corp., Healtheon/Web MD Corp., and Silicon Graphics, Inc. Currently he serves as Chairman of the Board for myCFO, which he also founded

Catmull-Clark Surfaces

- <u>Overview</u>
- <u>Specifying the Refinement Procedure</u>
- Example
- <u>Summary</u>

Overview

Ed Catmull and Jim Clark

- Following the methodology of Doo and Sabin
- Utilizing the subdivision of bicubic uniform B-spline surfaces for
 - rectangular meshes,
 - meshes of an arbitrary topology
- Generalizing the definition of a face point
- Modifying the method for calculating vertex points
- Specifying a method for reconnecting the points into a mesh

Specifying the Refinement Procedure

 Given a mesh of control points with an arbitrary topology, we can generalize the face point, edge point, vertex point specification from the uniform B-spline surface calculations

Specifying the Refinement Procedure

- For each face of the mesh, generate the new face points - which are the average of all the original points defining the face (We note that faces may have 3, 4, 5, or many points now defining them).
- Generate the new edge points which are calculated as the average of the midpoints of the original edge with the two new face points of the faces adjacent to the edge.

Specifying the Refinement Procedure

- Calculate the new vertex points which are calculated as the average of Q, 2R and [(n-3)/n]S
 - Q is the average of the new face points of all faces adjacent to the original face point
 - R is the average of the midpoints of all original edges incident on the original vertex point
 - S is the original vertex point
Specifying the Refinement Procedure

- The mesh is reconnected by the following method
 - Each new face point is connected to the new edge points of the edges defining the original face.
 - Each new vertex point is connected to the new edge points of all original edges incident on the original vertex point.



Example (1)



Example (1)



Example (1)



Connect new points to generate refined mesh

State Key Lab of CAD&CG

Example (2)



Example (2)



Example (2)



Connect new points to generate refined mesh

State Key Lab of CAD&CG

Example (3) --- 3 steps







State Key Lab of CAD&CG

Example (4)



Original Cube The 1st subdivision The 2nd subdivision



Summary

- We note that the new set of control points has the property that all faces have four sides.
- We also note that the vertices corresponding to the original control points retain the valence (the number of edges that are adjacent to the vertex).

Summary

 We note that any portion of the surface where we have a 4×4 array of control points in a rectangular topology, represents a bicubic uniform B-spline surface patch

Summary

• Extraordinary point: the valence is not four

 The limit of Catmull-Clark subdivision surface are piecewise uniform bicubic Bspline surface patches except for the Extraordinary point



Loop Surfaces

- <u>Overview</u>
- Loop Surfaces for Regular Meshes
- <u>Specifying the New Vertex Rules for</u>
 <u>Extraordinary Points</u>
- Examples

Charles Loop Researcher Microsoft Research Graphics Group



Overview

- Doo-Sabin surfaces: uniform biquadratic
 B-spline surface subdivision
- Catmull-Clark surfaces: bicubic uniform Bspline surface subdivision
- Loop surfaces: the quartic uniform box splines subdivision
 - a mesh of triangles



Loop Surfaces for Regular Meshes

- Given a triangular mesh, the Loop refinement scheme generates
 - vertex points: vertex mask
 - edge points: edge mask



Loop Surfaces for Regular Meshes

About edge mask: edge point is the average of the two centers of the faces that share the edge and the midpoint of the edge



Loop Surfaces for Regular Meshes

About the vertex mask: the vertex point is a convex combination of the points V (5/8), the original vertex, and Q(3/8) the average of the original points that share an edge with V

$$\mathbf{V}^{1} = \frac{10\mathbf{V} + \mathbf{Q}_{1} + \mathbf{Q}_{2} + \mathbf{Q}_{3} + \mathbf{Q}_{4} + \mathbf{Q}_{5} + \mathbf{Q}_{6}}{16}$$

$$= \frac{5}{8}\mathbf{V} + \frac{\mathbf{Q}_{1} + \mathbf{Q}_{2} + \mathbf{Q}_{3} + \mathbf{Q}_{4} + \mathbf{Q}_{5} + \mathbf{Q}_{6}}{16}$$

$$= \frac{5}{8}\mathbf{V} + \frac{6\mathbf{Q}}{16}$$

$$= \frac{5}{8}\mathbf{V} + \frac{3}{8}\mathbf{Q}$$

Specifying the New Vertex Rules for Extraordinary Points

• Extraordinary point (valence \neq 6):



$$\beta = \frac{1}{k} \left(\left(\frac{3}{8} + \frac{1}{4}\cos\frac{2\pi}{k}\right)^2 + \frac{3}{8} \right)$$

k: valence of the extraordinary points

Examples



Examples





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http://www.cad.zju.edu.cn/home/jqfeng/GM/GM06.zip