Preliminary Mathematics of Geometric Modeling (3)

Hongxin Zhang and Jieqing Feng

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State Key Lab of CAD&CG, Zhejiang University

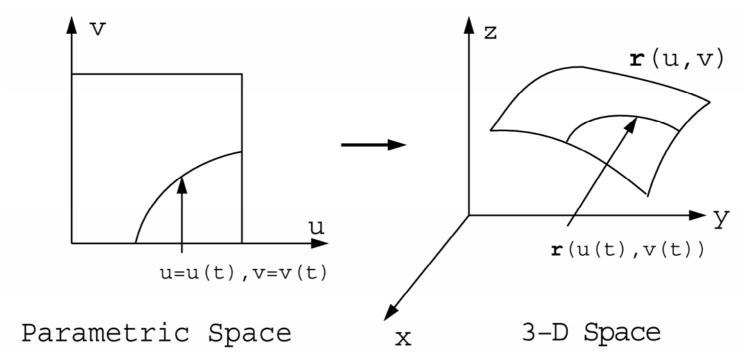
Differential Geometry of Surfaces

- Tangent plane and surface normal
- First fundamental form I (metric)
- Second fundamental form II (curvature)
- Principal curvatures
- Gaussian and mean curvatures
 - Explicit surfaces
 - Implicit surfaces
- Euler's theorem and Dupin's indicatrix

Tangent vector on the surface

A parametric surface $\mathbf{r}=\mathbf{r}(u,v)$

A curve u=u(t), v=v(t) in the parametric domain



Tangent vector on the surface

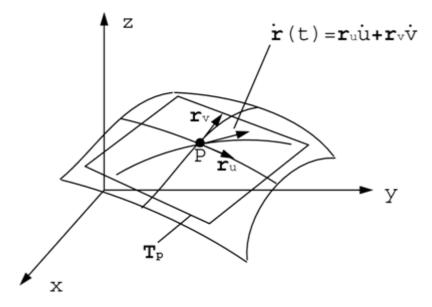
The tangent vector of the curve on the surface respect to the parameter *t* :

$$\mathbf{r}(t) = \mathbf{r}(u(t), v(t))$$
$$\dot{\mathbf{r}}(t) = \mathbf{r}_u \dot{u} + \mathbf{r}_v \dot{v}$$
$$\dot{u} = \dot{u}(t)$$
$$\dot{v} = \dot{v}(t)$$

where

Tangent plane on the surface

The *tangent plane* at point *P* can be considered as a union of the tangent vectors for all $\mathbf{r}(t)$ through *P*



The tangent plane at a point on a surface

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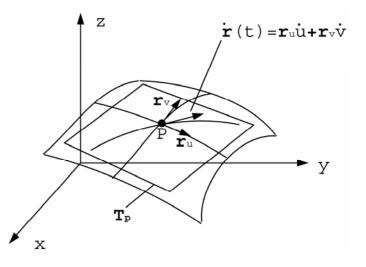
Tangent plane on the surface

Suppose: $P = \mathbf{r}(u_p, v_p)$

The equation of tangent plane at $\mathbf{r}(u_p, v_p)$:

$$\mathbf{T}_p(\mu,\nu) = \mathbf{r}(u_p,v_p) + \mu \mathbf{r}_u(u_p,v_p) + \nu \mathbf{r}_v(u_p,v_p)$$

Where μ , ν are parameter



Surface normal

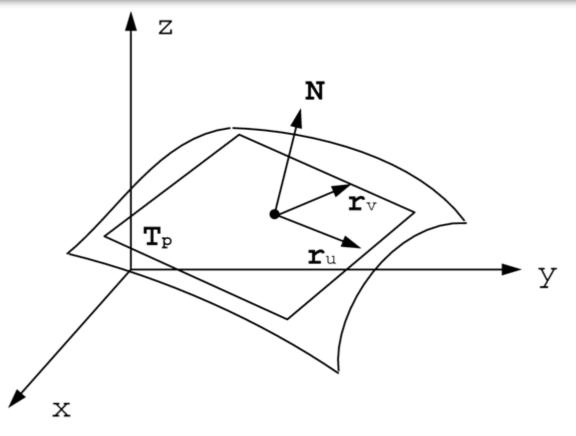
The *surface normal vector* is perpendicular to the tangent plane. The unit normal is

$$\mathbf{N} = rac{\mathbf{r}_u imes \mathbf{r}_v}{|\mathbf{r}_u imes \mathbf{r}_v|}$$

The implicit form of tangent surface is

$$(\mathbf{r} - \mathbf{r}(u_p, v_p)) \cdot \mathbf{N}(u_p, v_p) = 0$$

Surface normal



The normal to the point on a surface

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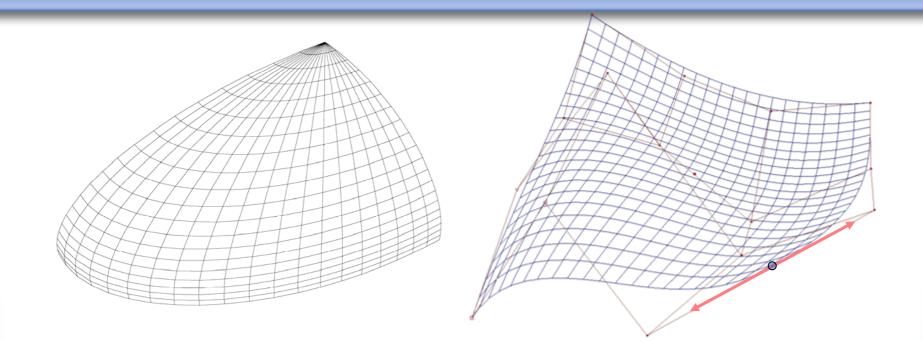
Regular point on the surface

Definition: A regular (ordinary) point *P* on a parametric surface is defined as a point where $\mathbf{r}_u \times \mathbf{r}_v \neq \mathbf{0}$. A point which is not a regular point is called a singular point.

Notes for

- Regular point:
 - 1. $\mathbf{r}_u \neq 0$ and $\mathbf{r}_v \neq 0$
 - 2. \mathbf{r}_u is not parallel to \mathbf{r}_v
- Singular point:
 - 1. Normal may exist at the singular point

Examples of singular point



 $\mathbf{r}_{\mu} = 0$ or $\mathbf{r}_{\nu} = 0$

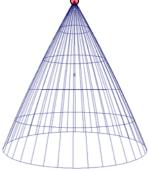
 $\mathbf{r}_u // \mathbf{r}_v$

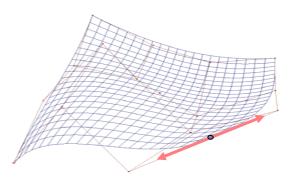
Types of singular points

 Essential singularities: specific features of the surface geometry

Apex of cone

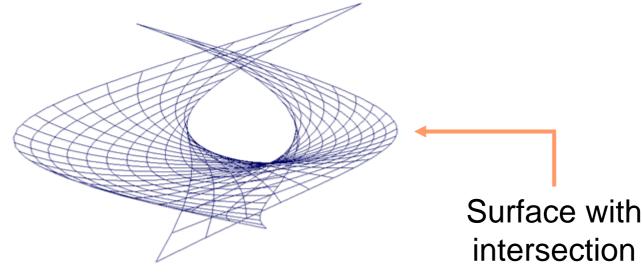
Artificial singularities
 parametrization





Regular surface

- Existence of a tangent plane everywhere on the surface
- Without self-intersection



Example: elliptic cone

Parametric form: $\mathbf{r} = (at\cos\theta, bt\sin\theta, ct)^T$ Where $0 \le \theta \le 2\pi$, $0 \le t \le l$, a, b, c are *constants*

$$\mathbf{r}_{\theta} = (-at\sin\theta, bt\cos\theta, 0)^T$$
 $\mathbf{r}_t = (a\cos\theta, b\sin\theta, c)^T$

$$|\mathbf{r}_{\theta} \times \mathbf{r}_{t}| = |bct \cos \theta \mathbf{e}_{x} + act \sin \theta \mathbf{e}_{y} - abt \mathbf{e}_{z}|$$
$$= \sqrt{t^{2}(b^{2}c^{2} \cos^{2} \theta + a^{2}c^{2} \sin^{2} \theta + a^{2}b^{2})}$$

The apex of the cone (t=0) is singular

Implicit surface: f(x,y,z)=0

Considering the two parametric curves on the surfaces

 $\mathbf{r}_1 = (x_1(t_1), y_1(t_1), z_1(t_1))$ $\mathbf{r}_2 = (x_2(t_2), y_2(t_2), z_2(t_2))$

The \mathbf{r}_1 and \mathbf{r}_2 intersect at point P

By substituting \mathbf{r}_1 and \mathbf{r}_2 into \mathbf{f} , we have

$$f(x_1(t_1), y_1(t_1), z(t_1)) = 0 \qquad f(x_2(t_2), y_2(t_2), z(t_2)) = 0 -$$

By differentiation with t_1 and t_2 respectively

$$f_x \frac{dx_1}{dt_1} + f_y \frac{dy_1}{dt_1} + f_z \frac{dz_1}{dt_1} = 0 \quad f_x \frac{dx_2}{dt_2} + f_y \frac{dy_2}{dt_2} + f_z \frac{dz_2}{dt_2} = 0$$

After simplification, we can deduce: $f_x : f_y : f_z =$ $\frac{dz_2}{dt_2} \frac{dy_1}{dt_1} - \frac{dz_1}{dt_1} \frac{dy_2}{dt_2} : \frac{dz_1}{dt_1} \frac{dx_2}{dt_2} - \frac{dz_2}{dt_2} \frac{dx_1}{dt_1} : \frac{dx_1}{dt_1} \frac{dy_2}{dt_2} - \frac{dx_2}{dt_2} \frac{dy_1}{dt_1}$

As we know

$$\frac{d\mathbf{r}_{1}(t_{1})}{dt_{1}} \times \frac{d\mathbf{r}_{2}(t_{2})}{dt_{2}}$$

$$= \left(\frac{dz_{2}}{dt_{2}}\frac{dy_{1}}{dt_{1}} - \frac{dz_{1}}{dt_{1}}\frac{dy_{2}}{dt_{2}}, \frac{dz_{1}}{dt_{1}}\frac{dx_{2}}{dt_{2}} - \frac{dz_{2}}{dt_{2}}\frac{dx_{1}}{dt_{1}}, \frac{dx_{1}}{dt_{1}}\frac{dy_{2}}{dt_{2}} - \frac{dx_{2}}{dt_{2}}\frac{dy_{1}}{dt_{1}}\right)^{T}$$

Thus the normal is the gradient of f, i.e. $\nabla f = (f_x, f_y, f_z)^T \swarrow \frac{d\mathbf{r}_1(t_1)}{dt_1} \times \frac{d\mathbf{r}_2(t_2)}{dt_2}$

Unit normal of the implicit surface

$$\mathbf{N} = \frac{(f_x, f_y, f_z)^T}{\sqrt{f_x^2 + f_y^2 + f_z^2}} = \frac{\nabla f}{|\nabla f|}$$

provided that $|\nabla f| \neq 0$

Tangent plane of implicit surface

The tangent plane of point $P(x_p, y_p, z_p)$ on the implicit surface f(x, y, z)=0 is

 $\nabla f \cdot (\mathbf{r} - P) = 0$

i.e.

$$f_x(x - x_p) + f_y(y - y_p) + f_z(z - z_p) = 0$$

$$\mathbf{r} = (x, y, z)$$

Example: elliptic cone

Elliptic cone in implicit form

$$f(x,y,z) = (\tfrac{x}{a})^2 + (\tfrac{y}{b})^2 - (\tfrac{z}{c})^2 = 0$$

The gradient (normal) is

$$\nabla f = (\frac{2x}{a^2}, \frac{2y}{b^2}, -\frac{2z}{c^2})^T$$

subject to $(x, y, z) \in f(x, y, z) = 0$

First fundamental form / (metric)

The differential arc length of parametric curve on the parametric surface

- Parametric surface r=r(u,v)
- Parametric curve defined the in parametric domain <u>u=u(t)</u>, <u>v=v(t)</u>
- The differential arc length of parametric curve

$$ds = \left|\frac{d\mathbf{r}}{dt}\right| dt = |\dot{\mathbf{r}}| dt = \sqrt{\dot{\mathbf{r}} \cdot \dot{\mathbf{r}}} dt$$

First fundamental form / (metric)

$$ds = \left| \frac{d\mathbf{r}}{dt} \right| dt = \left| \mathbf{r}_u \frac{du}{dt} + \mathbf{r}_v \frac{dv}{dt} \right| dt$$
$$= \sqrt{(\mathbf{r}_u \dot{u} + \mathbf{r}_v \dot{v}) \cdot (\mathbf{r}_u \dot{u} + \mathbf{r}_v \dot{v})} dt$$
$$= \sqrt{E du^2 + 2F du dv + G dv^2} ,$$
where $E = \mathbf{r}_u \cdot \mathbf{r}_u$, $F = \mathbf{r}_u \cdot \mathbf{r}_v$, $G = \mathbf{r}_v \cdot \mathbf{r}_v$

First fundamental form

• First fundamental form

$$I = ds^2 = d\mathbf{r} \cdot d\mathbf{r} = Edu^2 + 2Fdudv + Gdv^2$$

- E, F, G: first fundamental form coefficients
- E, F, G are important for intrinsic properties
- Alternative representation

$$I = \frac{1}{E} (E \, du + F \, dv)^2 + \frac{EG - F^2}{E} dv^2$$

First fundamental form

$$(\mathbf{a} \times \mathbf{b}) \cdot (\mathbf{c} \times \mathbf{d}) = (\mathbf{a} \cdot \mathbf{c})(\mathbf{b} \cdot \mathbf{d}) - (\mathbf{a} \cdot \mathbf{d})(\mathbf{b} \cdot \mathbf{c})$$

 $\mathbf{a} \times \mathbf{b} + (\mathbf{a} \times \mathbf{b}) = (\mathbf{a} \cdot \mathbf{a})(\mathbf{b} \cdot \mathbf{b}) - (\mathbf{a} \cdot \mathbf{b})^2$

Thus $(\mathbf{r}_u \times \mathbf{r}_v)^2 = (\mathbf{r}_u \times \mathbf{r}_v) \cdot (\mathbf{r}_u \times \mathbf{r}_v)$ $= (\mathbf{r}_u \cdot \mathbf{r}_u)(\mathbf{r}_v \cdot \mathbf{r}_v) - (\mathbf{r}_u \cdot \mathbf{r}_v)^2$ $= EG - F^2 > 0$

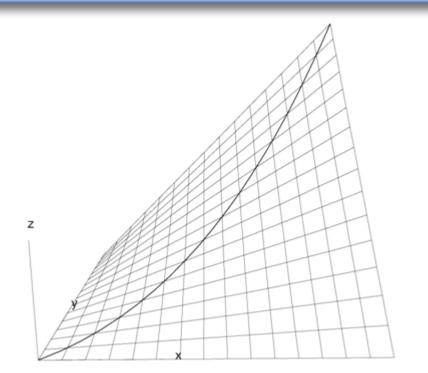
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First fundamental form

- $I \ge 0$ for arbitrary surface
 - *I* > 0: positive definite provided that the surface is regular
 - I = 0 iff du = 0 and dv = 0

Hyperbolic paraboloid: $\mathbf{r}(u,v)=(u,v,uv)^{\mathrm{T}}$ $0 \le u,v \le 1$ Curve: u=t, v=t. $0 \le t \le 1$

Aim: arc length of the curve on the surface



Hyperbolic paraboloid arc length along u=t, v=t

First fundamental form coefficients $\mathbf{r}_u = (1, 0, v)^T, \quad \mathbf{r}_v = (0, 1, u)^T$

$$E = \mathbf{r}_u \cdot \mathbf{r}_u = 1 + v^2$$
$$F = \mathbf{r}_u \cdot \mathbf{r}_v = uv$$
$$G = \mathbf{r}_v \cdot \mathbf{r}_v = 1 + u^2$$

First fundamental form coefficients along the curve

$$E = 1 + t^2$$
, $F = t^2$, $G = 1 + t^2$

The differential arc length of the curve

$$ds = \sqrt{E\dot{u}^2 + 2F\dot{u}\dot{v} + G\dot{v}^2}dt = 2\sqrt{t^2 + \frac{1}{2}}dt$$

The arc length of the curve $s = 2 \int_{0}^{1} \sqrt{t^{2} + \frac{1}{2}} dt$ $= \left| t\sqrt{t^{2} + \frac{1}{2}} + \frac{1}{2} log\left(t + \sqrt{t^{2} + \frac{1}{2}}\right) \right|_{1}^{2}$ $=\sqrt{\frac{3}{2}+\frac{1}{2}log(\sqrt{2}+\sqrt{3})}$

Application of first fundamental form: angle between curves on surface

- Two curves on a parametric surface $\mathbf{r}_1 = \mathbf{r}(u_1(t), v_1(t))$ $\mathbf{r}_2 = \mathbf{r}(u_2(t), v_2(t))$
 - Angle between r₁ and r₂ is the angle between their tangent vectors
 - Angle between two vectors a and b

 $\cos \omega = \frac{\mathbf{a} \cdot \mathbf{b}}{|\mathbf{a}||\mathbf{b}|} \quad \text{where}$

 $\mathbf{a} = \mathbf{r}_u du_1 + \mathbf{r}_v dv_1$

Application of first fundamental form: angle between curves on surface

Angle between curves on the surface

 $\cos \omega = \frac{E du_1 du_2 + F(du_1 dv_2 + dv_1 du_2) + G dv_1 dv_2}{\sqrt{E du_1^2 + 2F du_1 dv_1 + G dv_1^2} \sqrt{E du_2^2 + 2F du_2 dv_2 + G dv_2^2}}$ $= E \frac{du_1}{ds_1} \frac{du_2}{ds_2} + F\left(\frac{du_1}{ds_1} \frac{dv_2}{ds_2} + \frac{dv_1}{ds_1} \frac{du_2}{ds_2}\right) + G \frac{dv_1}{ds_1} \frac{dv_2}{ds_2} .$

• \mathbf{r}_1 and \mathbf{r}_2 is orthogonal ($\cos(\pi/2)=0$) if $Edu_1du_2 + F(du_1dv_2 + dv_1du_2) + Gdv_1dv_2 = 0$

Application of first fundamental form: angle between curves on surface

Special case: iso-parametric curves

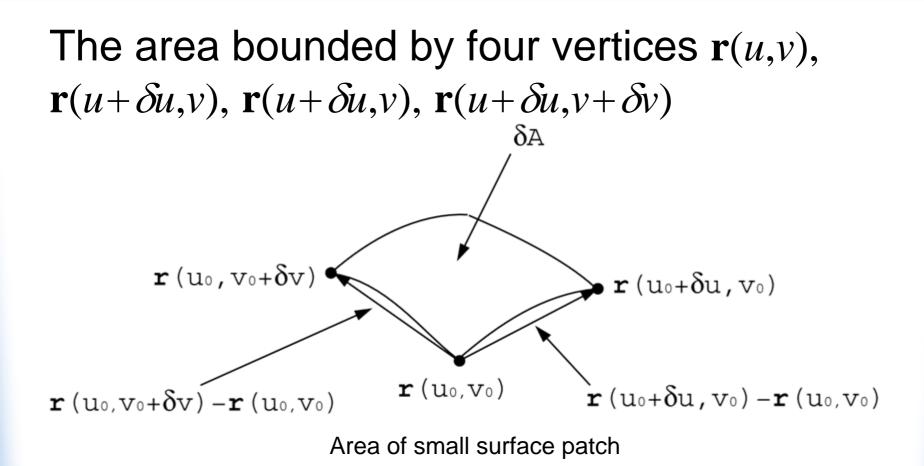
 $\mathbf{r}_1: u_1(t) = t, v_1(t) = 0$

$$\mathbf{r}_{2}: u_{2}(t)=0, v_{2}(t)=t$$

$$\cos\omega = \frac{\mathbf{r}_u \cdot \mathbf{r}_v}{|\mathbf{r}_u||\mathbf{r}_v|} = \frac{\mathbf{r}_u \cdot \mathbf{r}_v}{\sqrt{\mathbf{r}_u \cdot \mathbf{r}_u}\sqrt{\mathbf{r}_v \cdot \mathbf{r}_v}} = \frac{F}{\sqrt{EG}}$$

The iso-parametric curves are orthogonal if F=0

Application of first fundamental form: area of the surface patch



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Application of first fundamental form: area of the surface patch

The area bounded by four vertices $\mathbf{r}(u,v)$, $\mathbf{r}(u+\delta u,v)$, $\mathbf{r}(u+\delta u,v)$, $\mathbf{r}(u+\delta u,v+\delta v)$

$$\delta A = |\mathbf{r}_u \delta u \times \mathbf{r}_v \delta v| = \sqrt{EG - F^2} \delta u \delta v$$

In differential form

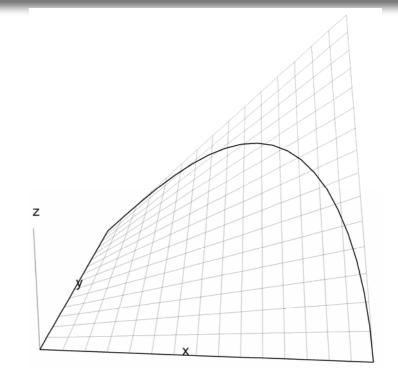
$$dA = \sqrt{EG - F^2} du dv$$

Recall

Example: area of surface patch

Hyperbolic paraboloid: $\mathbf{r}(u,v)=(u,v,uv)^{T}$ $0 \le u,v \le 1$ Bounded curves: u=0; v=0; $u^{2}+v^{2}=1$

Aim: Area of the surface patch bounded by the 3 curves?



Area bounded by positive *u* and *v* axes and a quarter circle

Example: area of surface patch

First fundamental form coefficients $\mathbf{r}_{u} = (1, 0, v)^{T}, \quad \mathbf{r}_{v} = (0, 1, u)^{T}$ $E = \mathbf{r}_u \cdot \mathbf{r}_u = 1 + v^2$ $F = \mathbf{r}_{u} \cdot \mathbf{r}_{v} = uv$ $G = \mathbf{r}_{v} \cdot \mathbf{r}_{v} = 1 + u^{2}$ r

$$A = \int_D \sqrt{1 + u^2 + v^2} du du$$

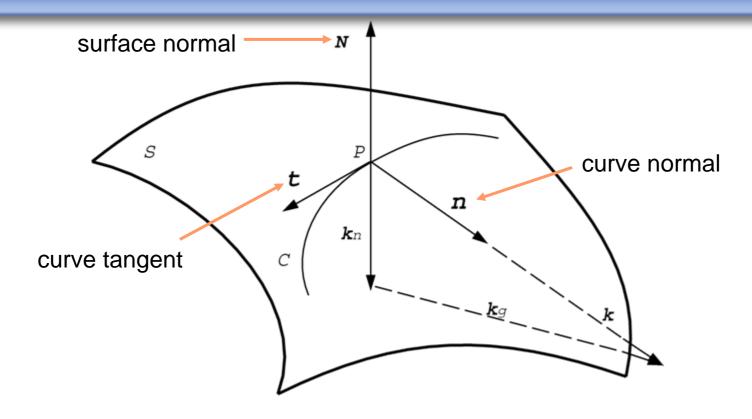
Example: area of surface patch

After reparametrization of the surface patch by setting $u=r\cos\theta$, $v=r\sin\theta$, we have

$$A = \int_0^{\frac{\pi}{2}} \int_0^1 \sqrt{1 + r^2} r \, d\theta \, dr = \frac{\pi}{6}(\sqrt{8} - 1)$$

 The second fundamental form quantify the curvatures of a surface

- Consider a curve C on surface S which passes through point P
 - The differential geometry of curve



Definition of normal curvature

The relationship between unit tangent vector \mathbf{t} and unit normal vector \mathbf{n} of the curve C at point P

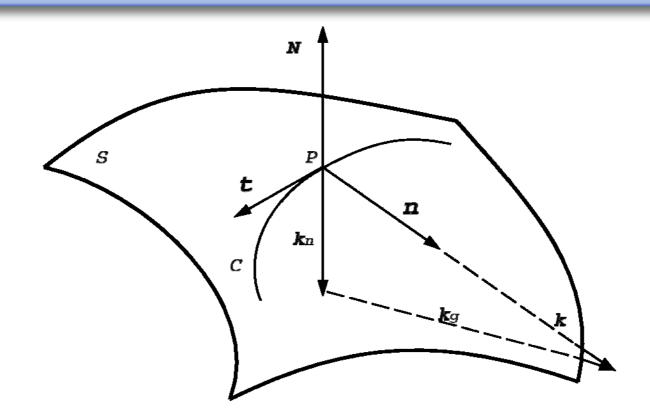
$$\mathbf{k} = \frac{d\mathbf{t}}{ds} = \kappa \mathbf{n} = \mathbf{k}_n + \mathbf{k}_g$$

- Normal curvature vector k_n: component of k of curve
 C in the surface normal direction
- Geodesic curvature vector k_g: component of k of curve C in the direction perpendicular to t in the surface tangent plane

The normal curvature vector can be expressed as

$$\mathbf{k}_n = \kappa_n \mathbf{N}$$

- K_n is called normal curvature of surface at point P in the direction t
- *K_n* is the magnitude of the projection of *k* onto the surface normal at *P*
- The sign of κ_n is determined by the orientation of the surface normal at *P*.



Definition of normal curvature

Differentiating $N \cdot t = 0$ along the curve respect to s:

$$\frac{d\mathbf{t}}{ds} \cdot \mathbf{N} + \mathbf{t} \cdot \frac{d\mathbf{N}}{ds} = 0$$

Combined with $\mathbf{k}_n = \kappa_n \mathbf{N}$, Thus

$$\begin{split} \kappa_n &= \frac{d\mathbf{t}}{ds} \cdot \mathbf{N} = -\mathbf{t} \cdot \frac{d\mathbf{N}}{ds} = -\frac{d\mathbf{r}}{ds} \cdot \frac{d\mathbf{N}}{ds} = -\frac{d\mathbf{r} \cdot d\mathbf{N}}{d\mathbf{r} \cdot d\mathbf{r}} \\ &= \frac{Ldu^2 + 2Mdudv + Ndv^2}{Edu^2 + 2Fdudv + Gdv^2} \;, \end{split}$$

where

 $L = -\mathbf{r}_{u} \cdot \mathbf{N}_{u}$ $M = -\frac{1}{2} (\mathbf{r}_{u} \cdot \mathbf{N}_{v} + \mathbf{r}_{v} \cdot \mathbf{N}_{u})$ $= -\mathbf{r}_{u} \cdot \mathbf{N}_{v} = -\mathbf{r}_{v} \cdot \mathbf{N}_{u}$ $N = -\mathbf{r}_{v} \cdot \mathbf{N}_{v}$

Since $\mathbf{r}_{\mu} \perp \mathbf{N}$ and $\mathbf{r}_{\nu} \perp \mathbf{N}$ $\mathbf{r}_{\mu} \cdot \mathbf{N} = 0$ and $\mathbf{r}_{\nu} \cdot \mathbf{N} = 0$ $d(\mathbf{r}_{u} \cdot \mathbf{N})/du = \mathbf{r}_{uu} \cdot \mathbf{N} + \mathbf{r}_{u} \cdot \mathbf{N}_{u} = 0$ $d(\mathbf{r}_{v}\cdot\mathbf{N})/du=\mathbf{r}_{uv}\cdot\mathbf{N}+\mathbf{r}_{v}\cdot\mathbf{N}_{u}=0$ $d(\mathbf{r}_{u}\cdot\mathbf{N})/dv = \mathbf{r}_{uv}\cdot\mathbf{N} + \mathbf{r}_{u}\cdot\mathbf{N}_{v} = 0$ $d(\mathbf{r}_v \cdot \mathbf{N})/dv = \mathbf{r}_v \cdot \mathbf{N} + \mathbf{r}_v \cdot \mathbf{N}_v = 0$

Alternative expression of *L*, *M* and *N* $L = \mathbf{r}_{uu} \cdot \mathbf{N} \quad M = \mathbf{r}_{uv} \cdot \mathbf{N} \quad N = \mathbf{r}_{vv} \cdot \mathbf{N}$

The second fundamental form II

$$II = Ldu^2 + 2Mdudv + Ndv^2$$

L, *M* and *N* are called second fundamental form coefficients

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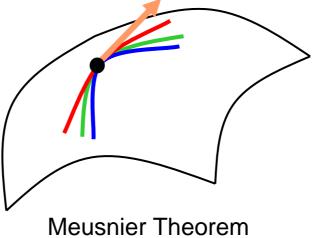
The normal curvature can be expressed as

$$\kappa_n = \frac{II}{I} = \frac{L + 2M\lambda + N\lambda^2}{E + 2F\lambda + G\lambda^2}$$

- λ=dv/du is the direction of the tangent line to
 C at P (in the surface parametric domain)
- κ_n at a given point *P* on the surface depends only on λ

Meusnier Theorem

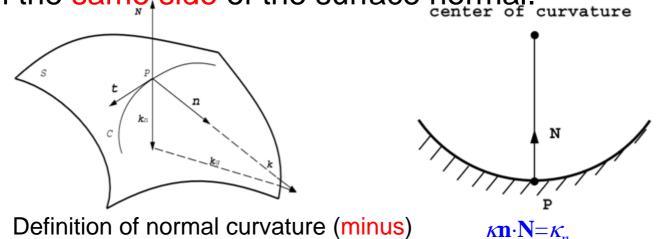
All curves lying on a surface *S* passing through a given point $p \in S$ with the same tangent line have the same normal curvature at this point.



About sign of normal curvature

• Convention (a): $\kappa \mathbf{n} \cdot \mathbf{N} = \kappa_n$

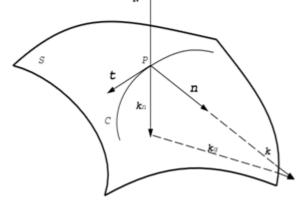
The normal curvature is positive when the center of the curvature of the normal section curve, which is a curve through P cut out by a plane that contains t and N, is on the same side of the surface normal.



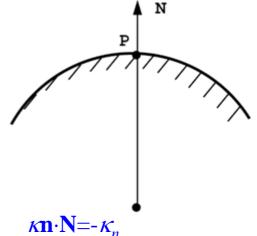
About sign of normal curvature

• Convention (b): $\kappa \mathbf{n} \cdot \mathbf{N} = -\kappa_n$

The normal curvature is positive when the center of the curvature of the normal section curve, which is a curve through P cut out by a plane that contains t and N, is on the opposite side of the surface normal.



Definition of normal curvature (positive)



About sign of normal curvature

- About convention (b)
 - The convention (b) is often used in the area of offset curves and surfaces in the context of NC machining

$$\mathbf{k}_n = -\kappa_n \mathbf{N}$$

$$\kappa_n = -\frac{II}{I} = -\frac{L + 2M\lambda + N\lambda^2}{E + 2F\lambda + G\lambda^2}$$

• Suppose *P* and *Q* on the surface $\mathbf{r}(u,v)$ $P = \mathbf{r}(u,v), \quad Q = \mathbf{r}(u+du,v+dv)$

d

$$\mathbf{r}(u+du,v+dv) = \mathbf{r}(u,v) + \mathbf{r}_u du + \mathbf{r}_v dv + \frac{1}{2}(\mathbf{r}_{uu} du^2 + 2\mathbf{r}_{uv} du dv + \mathbf{r}_{vv} dv^2) + \dots$$

Thus
$$\mathbf{PQ} = \mathbf{r}(u + du, v + dv) - \mathbf{r}(u, v) = \mathbf{r}_u du + \mathbf{r}_v dv$$

 $+ \frac{1}{2}(\mathbf{r}_{uu} du^2 + 2\mathbf{r}_{uv} du dv + \mathbf{r}_{vv} dv^2) + \dots$

Projecting PQ onto N

$$d = \mathbf{PQ} \cdot \mathbf{N} = (\mathbf{r}_u du + \mathbf{r}_v dv) \cdot \mathbf{N} + \frac{1}{2}II$$

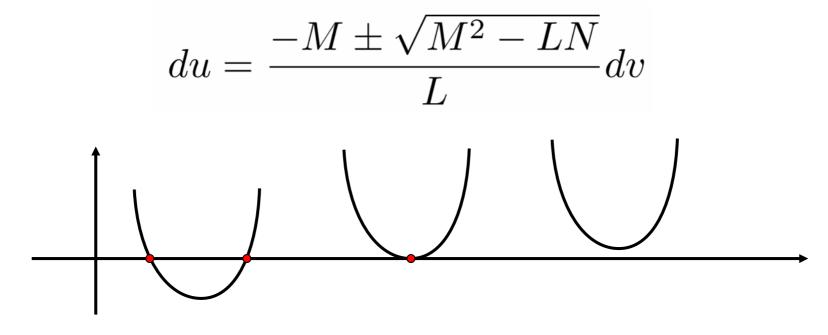
Finally

$$d = \frac{1}{2}II = \frac{1}{2}(Ldu^{2} + 2Mdudv + Ndv^{2})$$

Thus |II| is equal to twice the distance from Q to the tangent plane of the surface at P within second order terms.

Next, we determine the sign of II, i.e. Q lies in which side of tangent plane of P

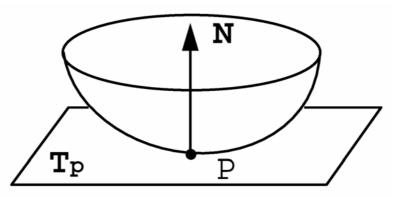
d=0: a quadratic equation interms of du or dvAssuming $L\neq 0$, we have



Point classification: Elliptic point

M^2 -LN<0 (Elliptic point) :

 There is no intersection between the surface and its tangent plane except at point *P*, e.g., ellipsoid

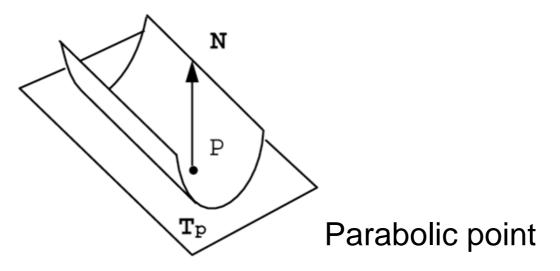


Elliptic point

Point classification: Parabolic point

M^2 -LN=0 (Parabolic point) :

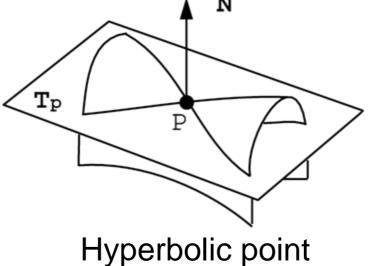
• There are double roots. The surface intersects its tangent plane with one line $du = -\frac{M}{L}dv$ which passes through point *P*, e.g., a circular cylinder



Point classification: Hyperbolic point

*M*²-*LN*>0 (Hyperbolic point) :

• There are two roots. The surface intersects its tangent plane with two lines $du = \frac{-M \pm \sqrt{M^2 - LN}}{L} dv$ which intersect at point *P*, e.g., a hyperbolic of revolution



Point classification: flat/planar point

L=*M*=*N*=0 (flat or planar point)

 The surface and the tangent plane have a contact of higher order than in the preceding cases

Point classification: other cases

- If L=0 and $N\neq 0$, we can solve for dv instead of du
- If L=N=0 and M≠0, we have 2Mdudv=0, thus the iso-parametric lines

u = const.

v = const.

will be the two intersection lines.

Download the courses

http://www.cad.zju.edu.cn/home/zhx/GM/GM03.zip