Learning with Local Consistency

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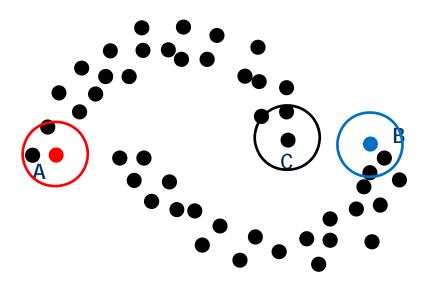


What is Local Consistency?

- Nearby points (neighbors) share similar properties.
- Traditional machine learning algorithms:
 - *k*-nearest neighbor classifier



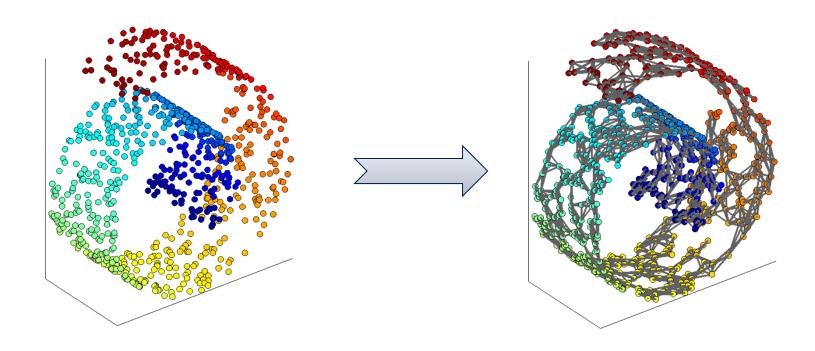
Local Consistency Assumption



- A lot of unlabeled data
- Local consistency
 - k-nearest neighbors
 - ϵ -neighbors



Local Consistency Assumption



- Put edges between neighbors (nearby data points)
- Two nodes in the graph connected by an edge share similar properties.



Local Consistency Assumption

- Similar properties
 - Labels
 - Representations
 - x: f(x)
- $W \in \mathbb{R}^{n \times n}$: weight matrix of the graph

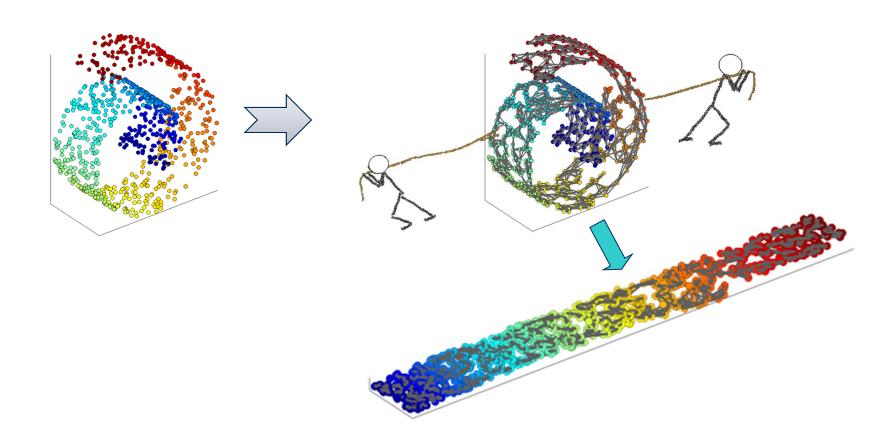
$$\min \frac{1}{2} \sum_{i,j} W_{ij} \left(f(\mathbf{x}_i) - f(\mathbf{x}_j) \right)^2 \qquad \mathbf{y}_i = f(\mathbf{x}_i)$$
$$\mathbf{y} = [y_1, \dots, y_n]^T$$
$$\min \mathbf{y}^T (D - W) \mathbf{y} \quad L \equiv D - W$$

$$\min y^T L y$$

$$s. t. \quad y^T D y = 1$$



Local Consistency and Manifold Learning



- Manifold learning
- We only need local consistency

$$\min \sum_{i,j} W_{ij} \left(f(\mathbf{x}_i) - f(\mathbf{x}_j) \right)^2$$



▶ How to use the local consistency idea?



Local Consistency in Semi-Supervised Learning

Supervised learning

$$f^* = \underset{f}{\operatorname{argmin}} \frac{1}{m} \sum_{i=1}^{m} l(\mathbf{x}_i, y_i, f) + \lambda ||f||^2$$

- Squared loss: ridge regression (regularized least squares)
- Hinge loss: SVM
- Semi-Supervised learning (with local consistency)

$$f^* = \underset{f}{\operatorname{argmin}} \frac{1}{m} \sum_{i=1}^{m} l(\mathbf{x}_i, y_i, f) + \lambda_1 ||f||^2 + \lambda_2 \sum_{i,j=1}^{n} W_{ij} \left(f(\mathbf{x}_i) - f(\mathbf{x}_j) \right)^2$$

Laplacian least squares and Laplacian SVM.



Manifold Regularization

Semi-Supervised learning (with local consistency)

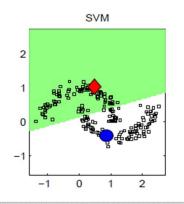
$$f^* = \underset{f}{\operatorname{argmin}} \frac{1}{m} \sum_{i=1}^{m} l(\mathbf{x}_i, y_i, f) + \lambda_1 ||f||^2 + \lambda_2 \sum_{i,j=1}^{n} W_{ij} \left(f(\mathbf{x}_i) - f(\mathbf{x}_j) \right)^2$$

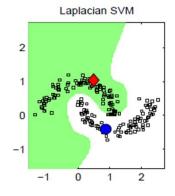
Laplacian least squares

$$a^* = (XX^T + \lambda_1 I + \lambda_2 X L X^T)^{-1} X y$$

Ridge regression (regularized least squares)

$$a^* = (XX^T + \lambda I)^{-1}Xy$$







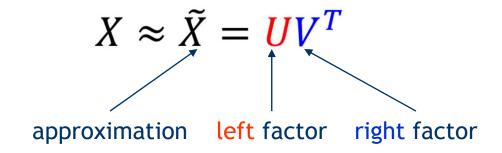
How to use the local consistency idea?

- Matrix factorization
 - Non-negative matrix factorization
- Topic modeling
 - Probabilistic latent semantic analysis
- Clustering
 - Gaussian mixture model



Matrix Factorization (Decomposition)

 $X = [x_1, \cdots, x_n] \in \mathcal{R}^{p \times n} \to X \approx UV^T$





Matrix Factorization (Decomposition)



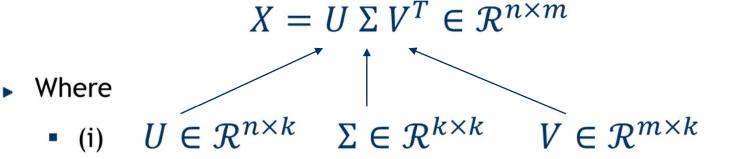
 $m \begin{bmatrix} x_{11} & x_{21} & \cdots & x_{n1} \\ x_{12} & x_{22} & \cdots & x_{n2} \\ x_{13} & x_{23} & \cdots & x_{n3} \\ \vdots & \vdots & & \vdots \\ x_{1m} & x_{2m} & \cdots & x_{nm} \end{bmatrix} \approx m \begin{bmatrix} u_{11} & \cdots & u_{k1} \\ u_{12} & \cdots & u_{k2} \\ u_{13} & \cdots & u_{k3} \\ \vdots & \vdots & & \vdots \\ u_{1m} & \cdots & u_{km} \end{bmatrix} \times k \begin{bmatrix} v_{11} & v_{12} & \cdots & v_{1n} \\ \vdots & \vdots & & \vdots \\ v_{k1} & v_{k2} & \cdots & v_{kn} \end{bmatrix}$

 $\left| \mathbf{x}_{i} \right| \approx v_{1i} \cdot \left| \mathbf{u}_{1} \right| + v_{2i} \cdot \left| \mathbf{u}_{2} \right| + \cdots + v_{ki} \cdot \left| \mathbf{u}_{k} \right|$



Singular Value Decomposition

For an arbitrary matrix X there exists a factorization (Singular Value Decomposition = SVD) as follows:



• (ii)
$$\mathbf{U}'\mathbf{U} = \mathbf{I}$$

$$V'V = I$$

Orthonormal columns

• (iii)
$$\Sigma = \operatorname{diag}(\sigma_1, \ldots, \sigma_k), \ \sigma_i \geq \sigma_{i+1}$$

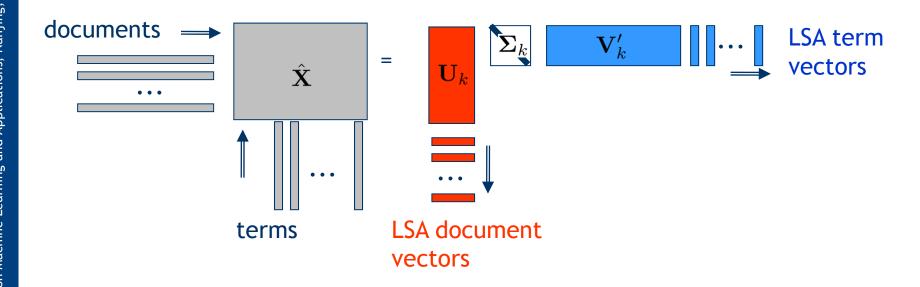
Singular values (ordered)

• (iv)
$$k = \operatorname{rank}(X)$$



Latent Semantic Analysis (Indexing)

The LSA via SVD can be summarized as follows:



- Document similarity
- Folding-in queries

$$\hat{\mathbf{q}} = \mathbf{\Sigma}_k^{-1} \mathbf{V}_k \mathbf{q}$$



Non-negative Matrix Factorization

$$X pprox \tilde{X} = UV^T, \min ||X - UV^T||^2$$

 $u_{ij} \ge 0, v_{ij} \ge 0$

▶ The Euclidean distance $||X - UV^T||^2$ is nonincreasing under the update rules

$$u_{ik} \leftarrow \frac{(XV)_{ik}}{(UV^TV)_{ik}} u_{ik} \qquad v_{jk} \leftarrow \frac{(X^TU)_{jk}}{(VU^TU)_{jk}} v_{jk}$$

Can we incorporate the local consistency idea?



Locally Consistent NMF

$$X \approx UV^T$$

If x_i and x_j are neighbors

$$\begin{bmatrix} \mathbf{x}_{i} \\ \mathbf{x}_{i} \end{bmatrix} = v_{1i} \cdot \begin{bmatrix} \mathbf{u}_{1} \\ \mathbf{u}_{1} \end{bmatrix} + v_{2i} \cdot \begin{bmatrix} \mathbf{u}_{2} \\ \mathbf{u}_{2} \end{bmatrix} + \cdots + v_{ki} \cdot \begin{bmatrix} \mathbf{u}_{k} \\ \mathbf{u}_{k} \end{bmatrix}$$

$$\begin{bmatrix} \mathbf{x}_{j} \\ \mathbf{x}_{j} \end{bmatrix} = v_{1j} \cdot \begin{bmatrix} \mathbf{u}_{1} \\ \mathbf{u}_{1} \end{bmatrix} + v_{2j} \cdot \begin{bmatrix} \mathbf{u}_{2} \\ \mathbf{u}_{2} \end{bmatrix} + \cdots + v_{k} \cdot \begin{bmatrix} \mathbf{u}_{k} \\ \mathbf{u}_{k} \end{bmatrix}$$

Neighbor: prior knowledge, label information, p-nearest neighbors ...



Locally Consistent NMF

$$\begin{bmatrix} \mathbf{x}_{i} \\ \end{bmatrix} = v_{1i} \cdot \begin{bmatrix} \mathbf{u}_{1} \\ \end{bmatrix} + v_{2i} \cdot \begin{bmatrix} \mathbf{u}_{2} \\ \end{bmatrix} + \cdots + v_{ki} \cdot \begin{bmatrix} \mathbf{u}_{k} \\ \end{bmatrix}$$

$$\begin{bmatrix} \mathbf{x}_{j} \\ \end{bmatrix} = v_{1j} \begin{bmatrix} \mathbf{u}_{1} \\ \end{bmatrix} + v_{2j} \cdot \begin{bmatrix} \mathbf{u}_{2} \\ \end{bmatrix} + \cdots + v_{kj} \cdot \begin{bmatrix} \mathbf{u}_{k} \\ \end{bmatrix}$$

$$\sum_{i,j} W_{ij} (f(\mathbf{x}_{i}) - f(\mathbf{x}_{j}))^{2} \qquad \min \sum_{k} \sum_{i,j} W_{ij} (v_{ki} - v_{kj})^{2}$$

$$\min \operatorname{Tr}(V^{T}LV)$$



Objective Function

NMF:
$$\min ||X - UV^T||^2$$

$$u_{ik} \leftarrow \frac{(XV)_{ik}}{(UV^TV)_{ik}} u_{ik} \qquad v_{jk} \leftarrow \frac{(X^TU)_{jk}}{(VU^TU)_{jk}} v_{jk}$$

GNMF: $\min ||X - UV^T||^2 + \lambda \text{Tr}(V^T L V)$

Graph regularized NMF

$$u_{ik} \leftarrow \frac{(XV)_{ik}}{(UV^TV)_{ik}} u_{ik} \quad v_{jk} \leftarrow \frac{(X^TU + \lambda WV)_{jk}}{(VU^TU + \lambda DV)_{jk}} v_{jk}$$



Clustering Results

K		
I	NMF	GNMF
4	81.0 ± 14.2	93.5 ± 10.1
6	74.3 ± 10.1	$92.4{\pm}6.1$
8	69.3±8.6	84.0 ± 9.6
10	69.4 ± 7.6	84.4 ± 4.9
12	69.0 ± 6.3	81.0 ± 8.3
14	67.6 ± 5.6	79.2 ± 5.2
16	66.0 ± 6.0	$76.8 {\pm} 4.1$
18	62.8 ± 3.7	76.0 ± 3.0
20	60.5	75.3
Avg.	68.9	82.5

K		
11	NMF	GNMF
5	95.5±10.2	98.5±2.8
10	83.6 ± 12.2	91.4 ± 7.6
15	79.9 ± 11.7	$93.4{\pm}2.7$
20	76.3 ± 5.6	$91.2{\pm}2.6$
25	75.0 ± 4.5	88.6 ± 2.1
30	71.9	88.6
Avg.	80.4	92.0

TDT2

- COIL₂₀
- Please check our papers for more details.
- http://www.zjucadcg.cn/dengcai/GNMF/index.html

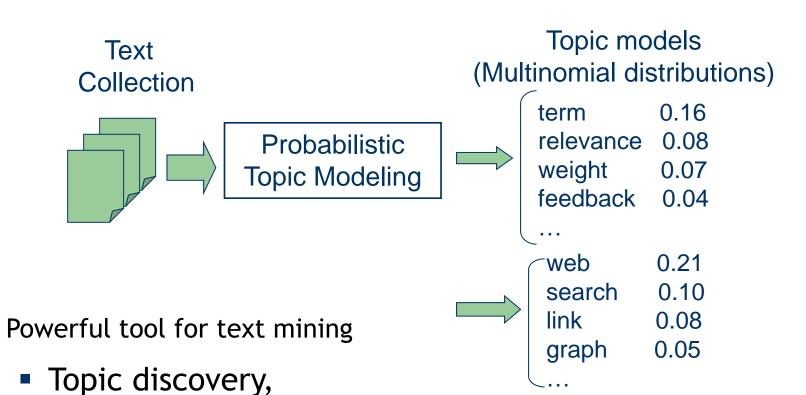


How to use the local consistency idea?

- Matrix factorization
 - Non-negative matrix factorization
- Topic modeling
 - Probabilistic latent semantic analysis
- Clustering
 - Gaussian mixture model



What is Topic Modeling



- - Many more ...

Summarization,

Opinion mining,



Language Model Paradigm in IR

- Probabilistic relevance model
 - Random variables

 $R_d \in \{0,1\}$: relevance of document d

 $q \subseteq \Sigma$: query, set of words

Bayes' rule

probability of generating a prior probability of relevance for query q to ask for relevant d document d (e.g. quality, popularity)

$$P(R_d = 1|q) = \frac{P(q|R_d = 1) \cdot P(R_d = 1)}{P(q)}$$

probability that document d is relevant for query q



Language Model Paradigm

$$P(R_d = 1|q) \propto P(q|R_d = 1) P(R_d = 1)$$
(1)

► First contribution: prior probability of relevance

simplest case: uniform (drops out for ranking)

 popularity: document usage statistics (e.g. library circulation records, download or access statistics, hyperlink structure)

- Second contribution: query likelihood
- query terms q are treated as a sample drawn from an (unknown) relevant document



Query Likelihood

$$P(q|R_d = 1) \equiv P(q|d)$$

$$q = (w_1, \cdots, w_q)$$

Independent Assumption

$$P(q|d) = \Pi_{w \in q} P(w|d)$$

P(w|d)?



Naive Approach

Terms



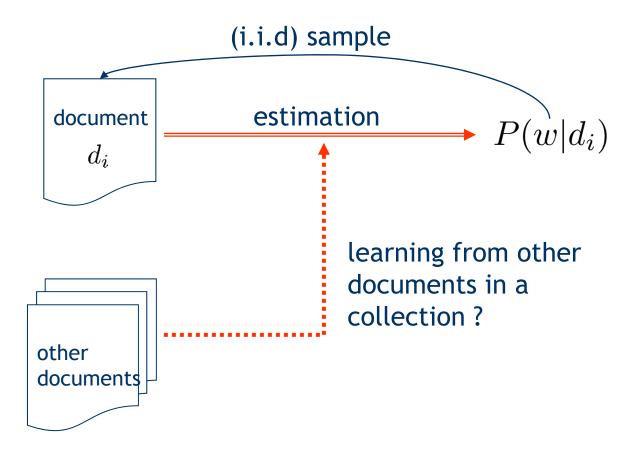
Maximum Likelihood Estimation

number of occurrences of term w in document d $\hat{P}_{\mathrm{ML}}(w|d) = \frac{n(d,w)}{\sum_{w'} n(d,w')}$

Zero frequency problem: terms not occurring in a document get zero probability



Estimation Problem

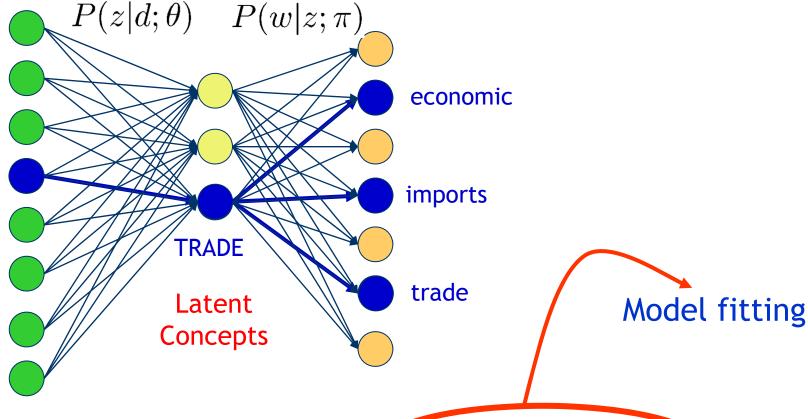


Crucial question: In which way can the document collection be utilized to improve probability estimates?



Probabilistic Latent Semantic Analysis





$$\hat{P}_{\text{LSA}}(w|d) = \sum_{z} P(w|z;\theta)P(z|d;\pi)$$



pLSA via Likelihood Maximization

Log-Likelihood

$$l(\theta, \pi; \mathbf{N}) = \sum_{d, w} n(d, w) \log(\sum_{z} P(w|z; \theta) P(z|d; \pi))$$

 Goal: Find model parameters that maximize the log-likelihood, i.e. maximize the average predictive probability for observed word occurrences (non-convex optimization problem)



Expectation Maximization Algorithm

E step: posterior probability of latent variables ("concepts")

$$P(z|d,w) = \frac{P(z|d;\pi)P(w|z;\theta)}{\sum_{z'} P(z'|d;\pi)P(w|z';\theta)}$$

Probability that the occurence of term w in document d can be "explained" by concept z

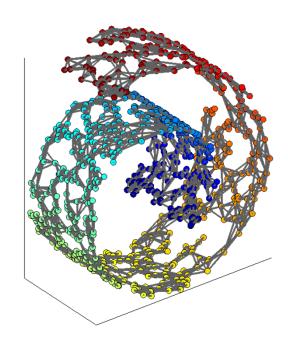
M step: parameter estimation based on "completed" statistics

$$P(w|z;\theta) \propto \sum_{d} n(d,w) P(z|d,w), \quad P(z|d;\pi) \propto \sum_{w} n(d,w) P(z|d,w)$$

$$P(z|d;\pi) \propto \sum_{w} n(d,w) P(z|d,w)$$



Local Consistency?



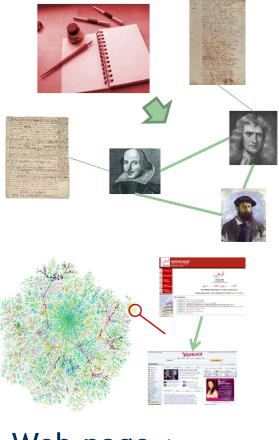
- Put edges between neighbors (nearby data points);
- Two nodes in the graph connected by an edge share similar properties.
- Network data
 - Co-author network, facebook, webpage



Text Collections with Network Structure

Blog articles + friend network

News + geographic network



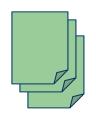
Web page + hyperlink structure



- Literature + coauthor/citation network
- Email + sender/receiver network
- •

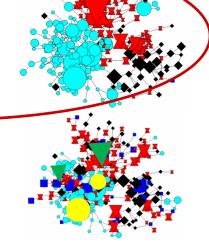


Importance of Topic Modeling on Network



Computer Science Literature Information Retrieval + Data Mining + Machine Learning, ...

Domain Review + Algorithm + Evaluation, ...





Intuitions

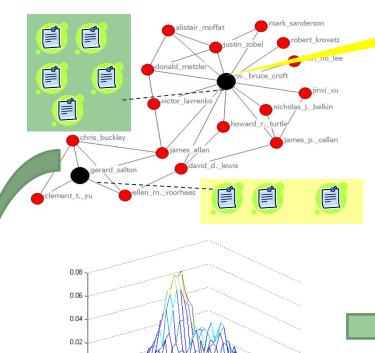
- People working on the same topic belong to the same "topical community"
- Good community: coherent topic + well connected
- A topic is semantically coherent if people working on this topic also collaborate a lot



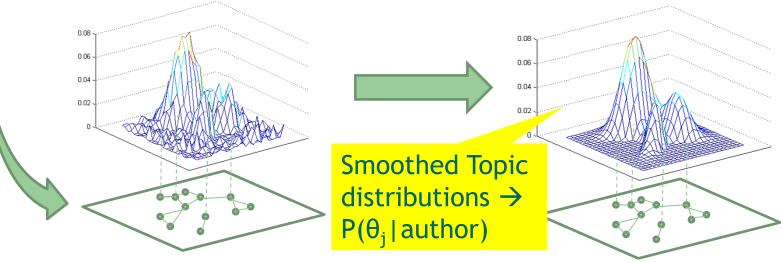


Social Network Context for Topic Modeling

e.g. coauthor network



- Context = author
- Coauthor = similar contexts
- Intuition: I work on similar topics to my neighbors



D. Cai, X. Wang, and X. He, Probabilistic Dyadic Data Analysis with Local and Global Consistency, ICML'09.

Q. Mei, D. Cai, D. Zhang, and C. Zhai, Topic Modeling with Network Regularization, WWW'08.



Objective Function

$$l(\theta, \pi; \mathbf{N}) = \sum_{d, w} n(d, w) \log(\sum_{z} P(w|z; \theta) P(z|d; \pi)) + \lambda R$$

$$\min \sum_{i,j} W_{ij} \left(f(\mathbf{x}_i) - f(\mathbf{x}_j) \right)^2 \qquad f(\mathbf{x}_i) = f(d_i) \equiv P(z|d_i)$$

$$D\left(P(z|d_i)||P(z|d_j)\right) = \sum_{z} P(z|d_i) \log \frac{P(z|d_i)}{P(z|d_j)}$$

$$R = -\frac{1}{2} \sum_{i,j} W_{ij} \left(D\left(P(z|d_i) || P(z|d_j) \right) + D\left(P(z|d_j) || P(z|d_i) \right) \right)^2$$



Parameter Estimation via EM

E step: posterior probability of latent variables ("concepts")

$$P(z_k|d_i,w_j) = \frac{P(w_j|z_k)P(z_k|d_i)}{\sum_{l=1}^K P(w_j|z_l)P(z_l|d_i)} \qquad \text{Same as PLSA}$$

M step: parameter estimation based on "completed" statistics

$$P(w_{j}|z_{k}) = \frac{\sum_{i=1}^{N} n(d_{i}, w_{j}) P(z_{k}|d_{i}, w_{j})}{\sum_{m=1}^{M} \sum_{i=1}^{N} n(d_{i}, w_{m}) P(z_{k}|d_{i}, w_{m})} \quad \text{Same as PLSA}$$

$$P(z_k \mid d_i) = ?$$



Parameter Estimation via EM

M step: parameter estimation based on "completed" statistics

$$\begin{bmatrix} P(z_{k} | d_{1}) \\ P(z_{k} | d_{2}) \\ \vdots \\ P(z_{k} | d_{N}) \end{bmatrix} = (\Omega + \lambda L)^{-1} \begin{bmatrix} \sum_{j=1}^{M} n(d_{1}, w_{j}) P(z_{k} | d_{1}, w_{j}) \\ \sum_{j=1}^{M} n(d_{2}, w_{j}) P(z_{k} | d_{2}, w_{j}) \\ \vdots \\ \sum_{j=1}^{M} n(d_{N}, w_{j}) P(z_{k} | d_{N}, w_{j}) \end{bmatrix}$$

$$\Omega = \begin{bmatrix} n(d_1) \\ \ddots \\ n(d_N) \end{bmatrix}$$
 $L = D - W,$
Graph Laplacian

If $\lambda = 0$

$$P(z_k \mid d_i) = \sum_{j=1}^{M} n(d_i, w_j) P(z_k \mid d_i, w_j) / n(d_i)$$
 Same as PLSA

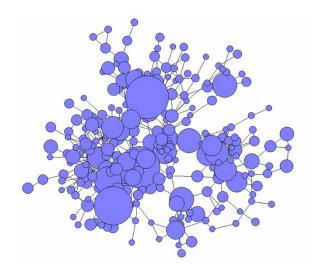


Experiments

Bibliography data and coauthor

networks

- DBLP: text = titles; network = coauthors
- Four conferences (expect 4 topics):
 SIGIR, KDD, NIPS, WWW





Topical Communities with PLSA

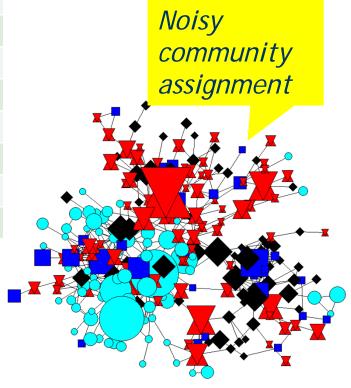
Topic 1		Topic 2		Topic 3		Topic 4	
term	0.02	peer	0.02	visual	0.02	interface	0.02
question	0.02	patterns	0.01	analog	0.02	towards	0.02
protein	0.01	mining	0.01	neurons	0.02	browsing	0.02
training	0.01	clusters	0.01	vlsi	0.01	xml	0.01
weighting	0.01	stream	0.01	motion	0.01	generation	0.01
multiple	0.01	frequent	0.01	chip	0.01	design	0.01
recognition	1 0.01	e	0.01	natural	0.01	engine	0.01
relations	0.01	page	0.01	cortex	0.01	service	0.01
library	0.01	gene	0.01	spike	0.01	social	0.01















Topical Communities with NetPLSA

Topic 1	Topic 2	Topic 3	Topic 4
retrieval 0.13	mining 0.11	neural 0.06	web 0.05
information 0.05	data 0.06	learning 0.02	services 0.03
document 0.03	discovery 0.03	networks 0.02	semantic 0.03
query 0.03	databases 0.02	recognition 0.02	services 0.03
text 0.03	rules 0.02	analog 0.01	peer 0.02
search 0.03	association 0.02	vlsi 0.01	ontologies 0.02
evaluation 0.02	patterns 0.02	neurons 0.01	rdf 0.02
user 0.02	frequent 0.01	gaussian 0.01	management 0.01
relevance 0.02	streams 0.01	network 0.01	ontology 0.01

Data mining

Machine learning Web Coherent community assignment

40

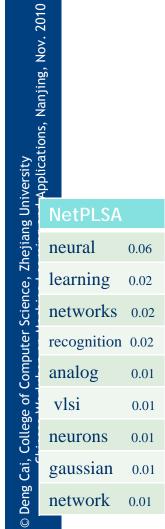
Information

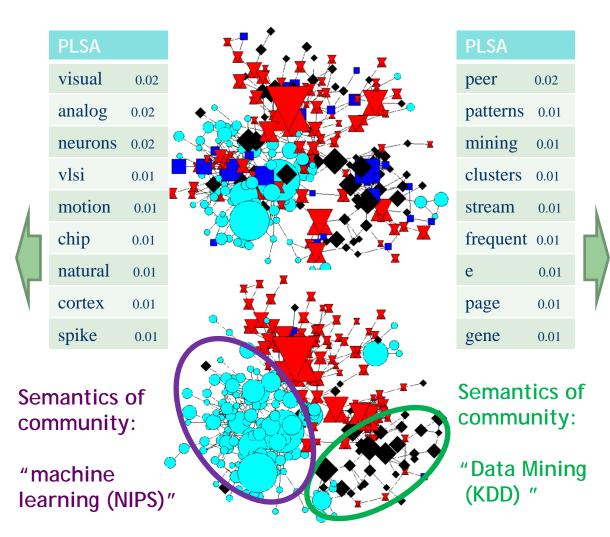
Retrieval





Coherent Topical Communities





NetPLSA	
mining	0.11
data	0.06
discovery	0.03
databases	0.02
rules	0.02
association	0.02
patterns	0.02
frequent	0.01
streams	0.01



For More Detials

Please check our papers

http://www.zjucadcg.cn/dengcai/LapPLSA/index.html

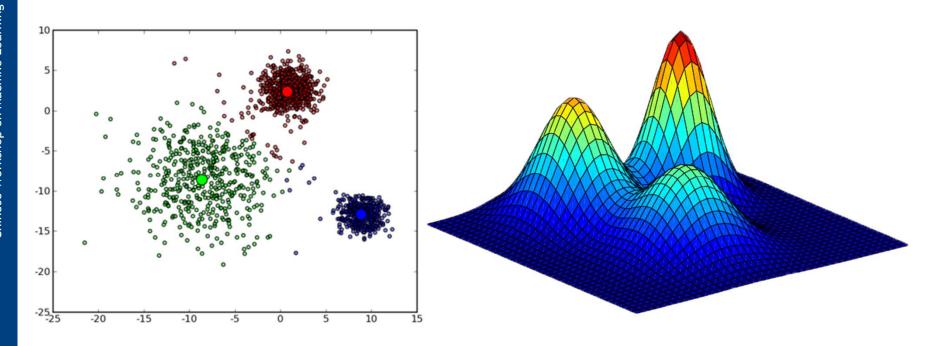


How to use the local consistency idea?

- Matrix factorization
 - Non-negative matrix factorization
- Topic modeling
 - Probabilistic latent semantic analysis
- Clustering
 - Gaussian mixture model



Gaussian Mixture Model (GMM) is one of the most popular clustering methods which can be viewed as a linear combination of different Gaussian components.





- Multivariate Gaussian
 - μ : mean of the distribution
 - Σ: covariance of the distribution

$$p(\mathbf{x}) = \mathcal{N}(\mathbf{x}; \boldsymbol{\mu}, \boldsymbol{\Sigma}) = \frac{1}{(2\pi)^{\frac{d}{2}} |\boldsymbol{\Sigma}|^{\frac{1}{2}}} \exp\left\{-\frac{1}{2} (\mathbf{x} - \boldsymbol{\mu})^T \boldsymbol{\Sigma}^{-1} (\mathbf{x} - \boldsymbol{\mu})\right\}$$

Maximum likelihood estimation

$$\widehat{\boldsymbol{\mu}} = \frac{1}{n} \sum_{i=1}^{n} \boldsymbol{x}_{i}$$

$$\widehat{\boldsymbol{\Sigma}} = \frac{1}{n} \sum_{i=1}^{n} (\boldsymbol{x}_{i} - \widehat{\boldsymbol{\mu}}) (\boldsymbol{x}_{i} - \widehat{\boldsymbol{\mu}})^{T}$$



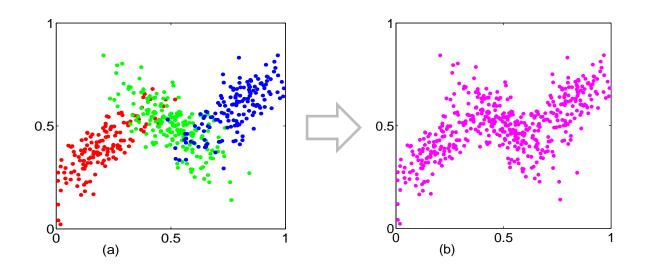
- Linear combination of Gaussians
 - Assumption: K Gaussians, each has a contribution of π_k to the data points

$$\begin{cases} p(\mathbf{x}; \mathbf{\Theta}) = \sum_{k=1}^{K} \pi_k p_k(\mathbf{x}; \mathbf{\theta}_k) \\ \mathbf{\Theta} = \{\pi_1, \cdots, \pi_K, \mathbf{\theta}_1, \cdots, \mathbf{\theta}_K\}, \sum_{k=1}^{K} \pi_k = 1, \pi_k \in [0, 0.5] \\ p_k(\mathbf{x}; \mathbf{\theta}_k) = \mathcal{N}(\mathbf{x}; \boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k) \end{cases}$$

• Parameters to be estimated: π_k , μ_k , Σ_k



- The process of generating a data point
 - first pick one of the components with probability π_k
 - then draw a sample x_i from that component distribution
- Each data point is generated by one of k components





► The log-likelihood function:

$$\log \prod_{i=1}^{N} p(\mathbf{x}^{(i)}; \mathbf{\Theta}) = \sum_{i=1}^{N} \log \left(\sum_{k=1}^{K} \pi_{k} \mathcal{N}(\mathbf{x}^{(i)}; \boldsymbol{\mu}_{k}, \boldsymbol{\Sigma}_{k}) \right)$$

Using EM algorithm:

$$l(\boldsymbol{\theta}) = \sum_{i=1}^{M} \sum_{\mathbf{z}^{(i)}} Q^{i}(\mathbf{z}^{(i)}) \log \frac{p(\mathbf{x}^{(i)}, \mathbf{z}^{(i)}; \boldsymbol{\theta})}{Q^{i}(\mathbf{z}^{(i)})}$$

$$\equiv \sum_{i=1}^{M} \sum_{k=1}^{K} Q^{i} \left(\mathbf{z}_{k}^{(i)} \right) \log \pi_{k} \mathcal{N} \left(\mathbf{x}^{(i)}; \boldsymbol{\mu}_{k}, \boldsymbol{\Sigma}_{k} \right)$$



E-step:

$$Q^{i}\left(\mathbf{z}_{k}^{(i)}\right) = p\left(\mathbf{z}_{k}^{(i)}|\mathbf{x}^{(i)};\mathbf{\Theta}\right)$$
$$= \frac{\pi_{k}\mathcal{N}\left(\mathbf{x}^{(i)};\boldsymbol{\mu}_{k},\boldsymbol{\Sigma}_{k}\right)}{\sum_{k=1}^{K}\pi_{k}\mathcal{N}\left(\mathbf{x}^{(i)};\boldsymbol{\mu}_{k},\boldsymbol{\Sigma}_{k}\right)}$$

- M-step:
 - Take the derivative of the complete log likelihood to obtain estimates for π_k , μ_k , Σ_k directly

$$\pi_{k} = \frac{\sum_{i=1}^{M} Q^{i} \left(\mathbf{z}_{k}^{(i)}\right)}{M}$$

$$\mu_{k} = \frac{\sum_{i=1}^{M} \mathbf{x}^{(i)} Q^{i} \left(\mathbf{z}_{k}^{(i)}\right)}{\sum_{i=1}^{M} Q^{i} \left(\mathbf{z}_{k}^{(i)}\right)}$$

$$\Sigma_{k} = \frac{\sum_{i=1}^{M} (\mathbf{x}^{(i)} - \boldsymbol{\mu}_{k}) (\mathbf{x}^{(i)} - \boldsymbol{\mu}_{k})^{T} Q^{i} \left(\mathbf{z}_{k}^{(i)}\right)}{\sum_{i=1}^{M} Q^{i} \left(\mathbf{z}_{k}^{(i)}\right)}$$

▶ Do the iterations until convergence, then $Q^i\left(\mathbf{z}_k^{(i)}\right)$ can be used for clustering



Objective Function

$$\min \sum_{i,j} W_{ij} \left(f(\mathbf{x}_i) - f(\mathbf{x}_j) \right)^2 \qquad f(\mathbf{x}_i) \equiv P(z|\mathbf{x}_i)$$

$$D\left(P(z|\mathbf{x}_i)||P(z|\mathbf{x}_j)\right) = \sum_{z} P(z|\mathbf{x}_i) \log \frac{P(z|\mathbf{x}_i)}{P(z|\mathbf{x}_j)}$$

$$\mathbf{R} = -\frac{1}{2} \sum_{i,j} W_{ij} \left(D\left(P(z|\mathbf{x}_i) || P(z|\mathbf{x}_j) \right) + D\left(P(z|\mathbf{x}_j) || P(z|\mathbf{x}_i) \right) \right)^2$$

$$\sum_{i=1}^{N} \log \left(\sum_{k=1}^{K} \pi_k \mathcal{N} (\boldsymbol{x}^{(i)}; \boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k) \right) + \lambda \boldsymbol{R}$$



EM Equations

E-step: $P(c_k \mid x_i) = \frac{\pi_k \mathcal{N}(x_i \mid \mu_k, \Sigma_k)}{\sum_{k=1}^{K} \pi_j \mathcal{N}(x_i \mid \mu_j, \Sigma_j)}$

M-step:

$$\begin{aligned}
S_{i,k} &= (x_i - \mu_k)(x_i - \mu_k)^T \\
\pi_k &= \frac{\sum_{i=1}^{N} P(c_k \mid x_i)}{N} \\
\mu_k &= \frac{\sum_{i=1}^{N} N_i P(c_k \mid x_i)}{N_k} \\
\Sigma_k &= \frac{\sum_{i=1}^{N} P(c_k \mid x_i) S_{i,k}}{N_k} \\
- \frac{\sum_{i,j=1}^{N} (P(c_k \mid x_i) - P(c_k \mid x_j))(x_i - x_j) W_{ij}}{2N_k} \\
- \frac{\lambda \sum_{i,j=1}^{N} (P(c_k \mid x_i) - P(c_k \mid x_j))(S_{i,k} - S_{j,k}) W_{ij}}{2N_k} \\
- \frac{\lambda \sum_{i,j=1}^{N} (P(c_k \mid x_i) - P(c_k \mid x_j))(S_{i,k} - S_{j,k}) W_{ij}}{2N_k} \\
- \frac{\lambda \sum_{i,j=1}^{N} (P(c_k \mid x_i) - P(c_k \mid x_j))(S_{i,k} - S_{j,k}) W_{ij}}{2N_k} \\
- \frac{\lambda \sum_{i,j=1}^{N} (P(c_k \mid x_i) - P(c_k \mid x_j))(S_{i,k} - S_{j,k}) W_{ij}}{2N_k} \\
- \frac{\lambda \sum_{i,j=1}^{N} (P(c_k \mid x_i) - P(c_k \mid x_j))(S_{i,k} - S_{j,k}) W_{ij}}{2N_k} \\
- \frac{\lambda \sum_{i,j=1}^{N} (P(c_k \mid x_i) - P(c_k \mid x_j))(S_{i,k} - S_{j,k}) W_{ij}}{2N_k} \\
- \frac{\lambda \sum_{i,j=1}^{N} (P(c_k \mid x_i) - P(c_k \mid x_j))(S_{i,k} - S_{j,k}) W_{ij}}{2N_k} \\
- \frac{\lambda \sum_{i,j=1}^{N} (P(c_k \mid x_i) - P(c_k \mid x_j))(S_{i,k} - S_{j,k}) W_{ij}}{2N_k} \\
- \frac{\lambda \sum_{i,j=1}^{N} (P(c_k \mid x_i) - P(c_k \mid x_j))(S_{i,k} - S_{j,k}) W_{ij}}{2N_k} \\
- \frac{\lambda \sum_{i,j=1}^{N} (P(c_k \mid x_i) - P(c_k \mid x_j))(S_{i,k} - S_{j,k}) W_{ij}}{2N_k} \\
- \frac{\lambda \sum_{i,j=1}^{N} (P(c_k \mid x_i) - P(c_k \mid x_j))(S_{i,k} - S_{j,k}) W_{ij}}{2N_k} \\
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- \frac{\lambda \sum_{i,j=1}^{N} (P(c_k \mid x_i) - P(c_k \mid x_j))(S_{i,k} - S_{j,k}) W_{ij}}{2N_k} \\
- \frac{\lambda \sum_{i,j=1}^{N} (P(c_k \mid x_i) - P(c_k \mid x_j))(S_{i,k} - S_{j,k}) W_{ij}}{2N_k} \\
- \frac{\lambda \sum_{i,j=1}^{N} (P(c_k \mid x_i) - P(c_k \mid x_j))(S_{i,k} - S_{j,k}) W_{ij}}{2N_k} \\
- \frac{\lambda \sum_{i,j=1}^{N} (P(c_k \mid x_i) - P(c_k \mid x_i) - P(c_k \mid x_i) - P(c_k \mid x_i)}{2N_k} \\
- \frac{\lambda \sum_{i,j=1}^{N} (P(c_k \mid x_i) - P(c_k \mid x_i) - P(c_k \mid x_i) - P(c_k \mid x_i)}{2N_k} \\
- \frac{\lambda \sum_{i,j=1}^{N} (P(c_k \mid x_i) - P(c_k \mid x_i) - P(c_k \mid x_i) - P(c_k \mid x_i)}{2N_k} \\
- \frac{\lambda \sum_{i,j=1}^{N} (P(c_k \mid x_i) - P(c_k \mid x_i) - P(c_k \mid x_i) - P(c_k \mid x_i)}{2N_k} \\
- \frac{\lambda \sum_{i,j=1}^{N} (P(c_k \mid x_i) - P(c_k \mid x_i) - P(c_k \mid x_i) - P(c_k \mid x_i)}{2N_k} \\
- \frac{\lambda \sum_{i,j=1}^{N} (P(c_k \mid x_i) - P(c_k \mid x_i) - P(c_k \mid x_i)}{2N_k} \\
- \frac{$$

$$\pi_{k} = \frac{\sum_{i=1}^{N} P(c_{k} \mid x_{i})}{N}$$

$$N_{k} = \sum_{i=1}^{N} P(c_{k} \mid x_{i})$$

$$N_{k} = \sum_$$



Experiment

7 Real Data sets:

- •The Yale face image database.
- •The Waveform model described in "The Elements of Statistical Learning".
- •The Vowels data set which has steady state vowels of British English.
- •The Libras movement data set containing hand movement pictures.
- •The Control Charts data set consisting control charts.
- •The Cloud data set is a simple 2 classes problem.
- •The Breast Cancer Wisconsin data set computed from a digitized image of a fine needle aspirate (FNA) of a breast mass. They describe characteristics of the cell nuclei present in the image.



Clustering Results

Data set	LCGMM	GMM	K-means	Ncut	size	# of features	# of classes
Yale	54.3	29.1	51.5	54.6	165	4096	15
Libras	50.8	35.8	44.1	48.6	800	21	3
Chart	70.0	56.8	61.5	58.8	990	10	11
Cloud	100.0	96.2	74.4	61.5	360	90	15
Breast	95.5	94.7	85.4	88.9	600	60	6
Vowel	36.6	31.9	29.0	29.1	2048	10	2
Waveform	75.3	76.3	51.9	52.3	569	30	2



The Take-home Messages

- Local consistency is a very useful idea.
- It is very simple.
 - Nearby points (neighbors) share similar properties.

$$\min \sum_{i,j} W_{ij} \left(f(\boldsymbol{x}_i) - f(\boldsymbol{x}_j) \right)^2$$

- It can be put everywhere (with a lot of unlabeled data)
 - The key: how to optimize the regularized objective function.



Thanks!